



Emulators of Climate Models

12.S992 AI for Climate Action

Spring 2026

Speaker: Abigail Bodner

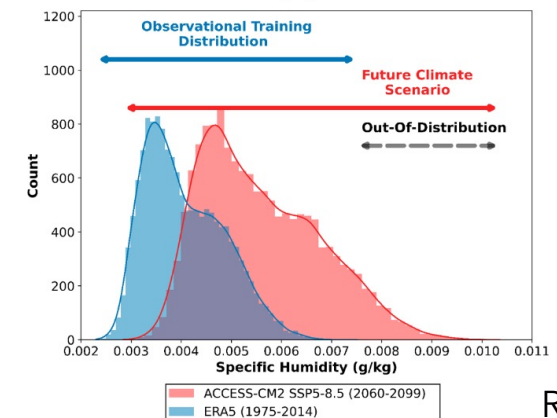
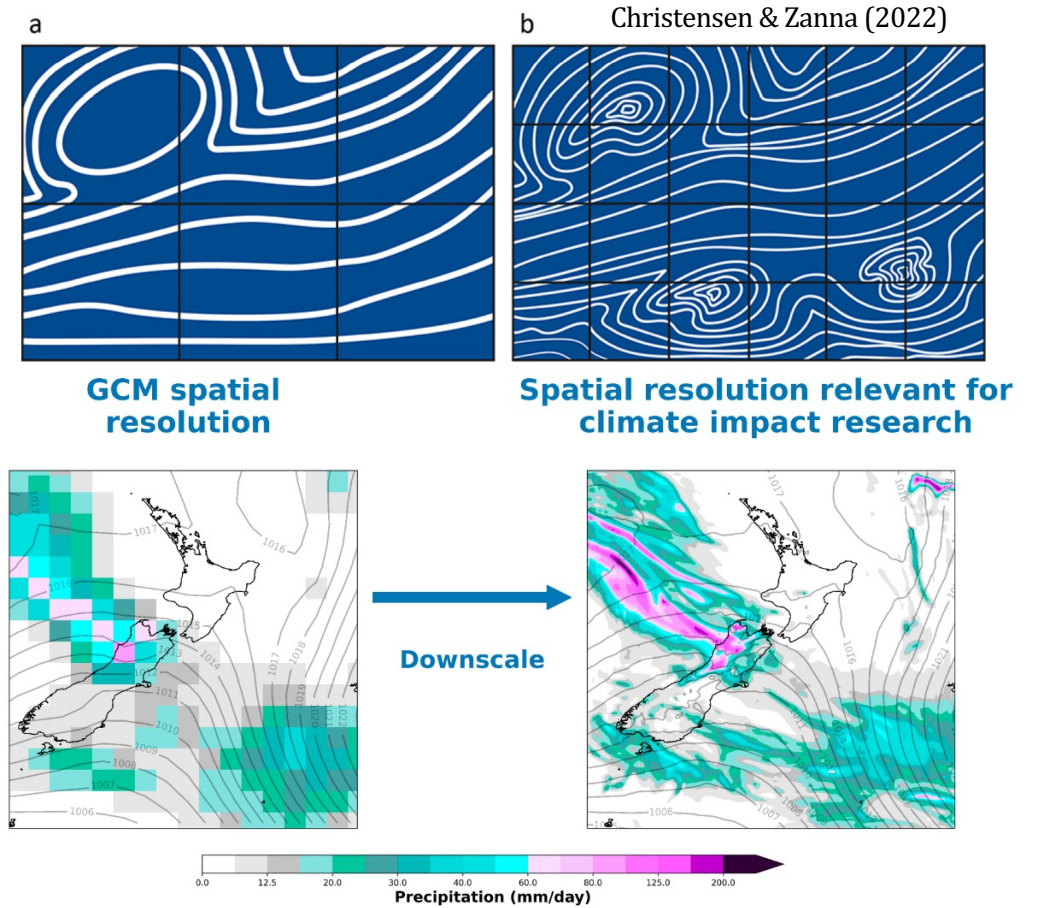
Reminder: Super-resolution

Also known as “upsampling” or “downscaling”

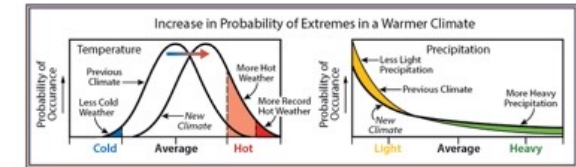
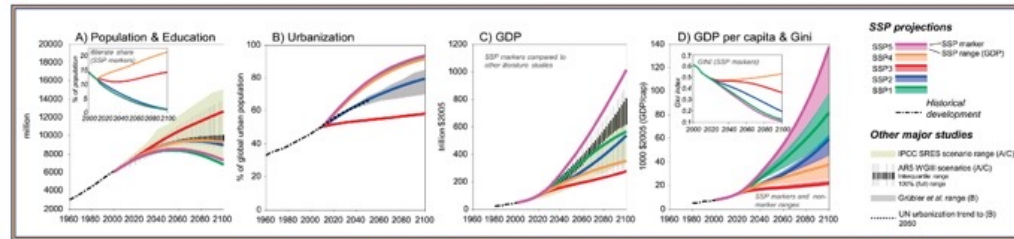
The process of going from a low-resolution (LR) field to a fine-resolution (FR) equivalent

Challenges

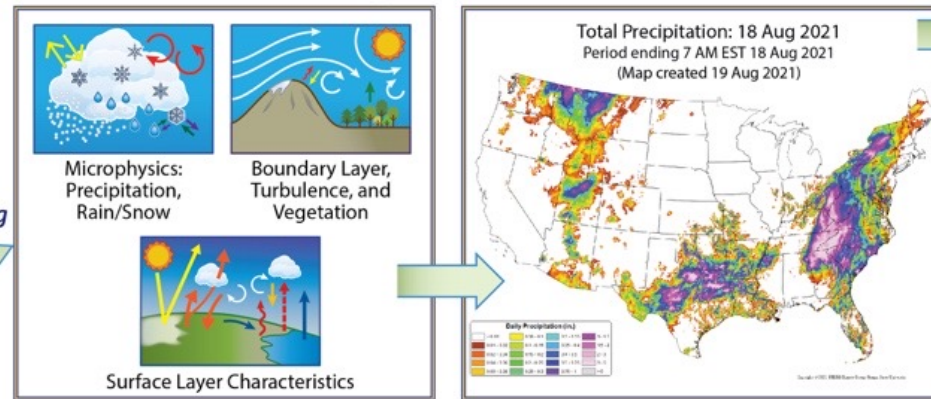
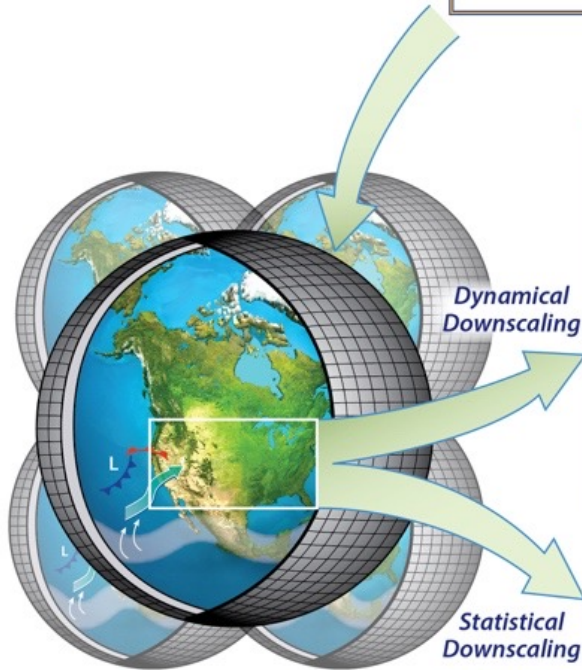
- No feedback of FR back onto low resolution evolution (recall parameterizations)
- Requires that predicted FR remains physically consistent
- Desired that captures extremes in FR
- Performs well out of distribution



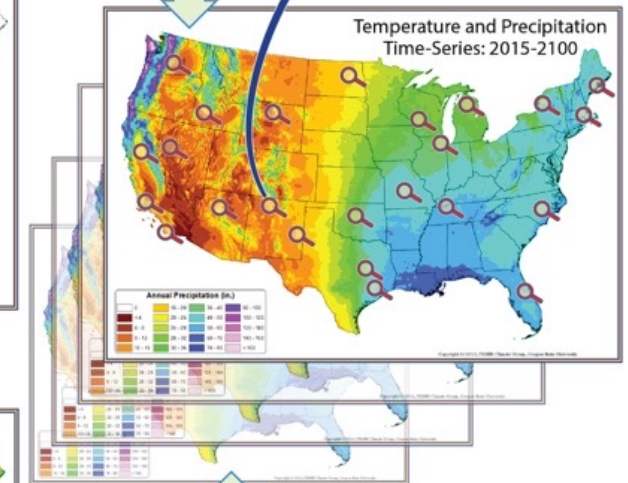
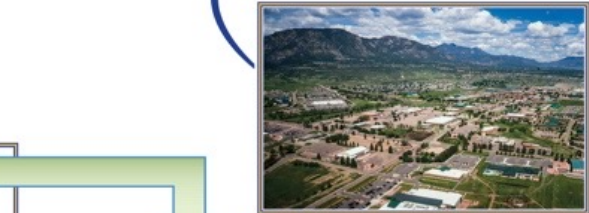
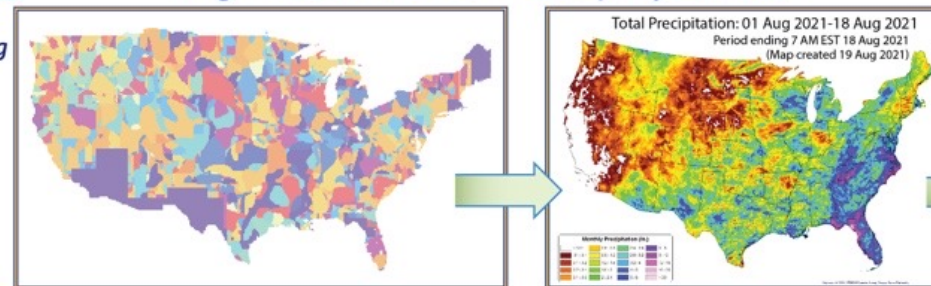
Dynamical vs statistical downscaling



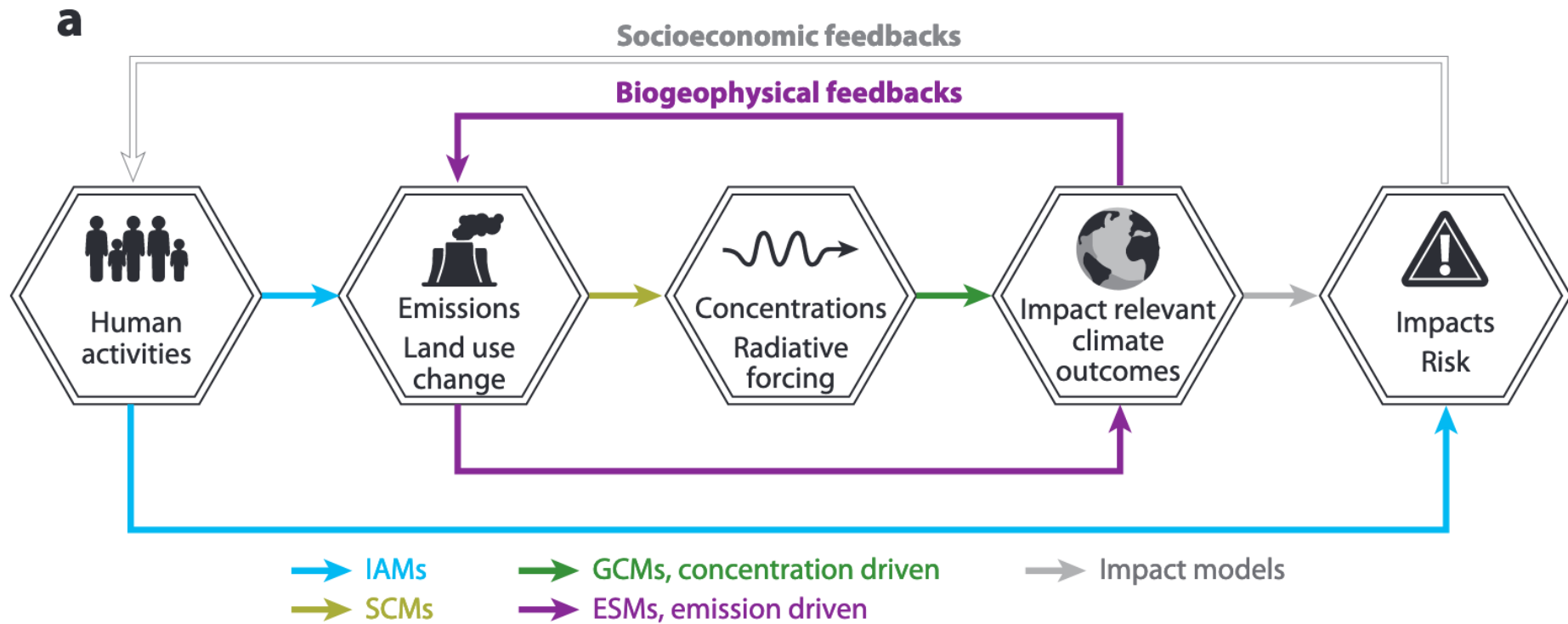
Understand physics and feedbacks affecting local changes in extreme weather



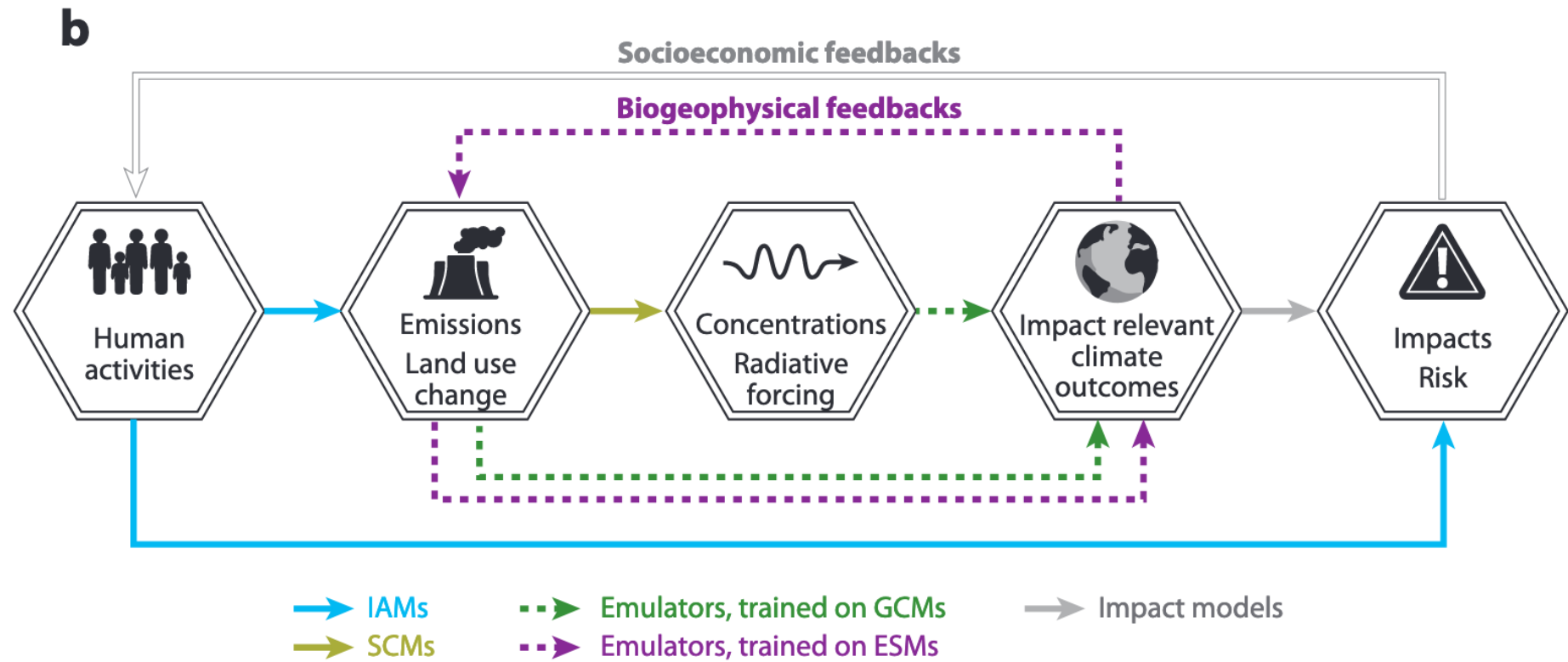
Evaluate physics and feedbacks in high-resolution climate projections



Emulators

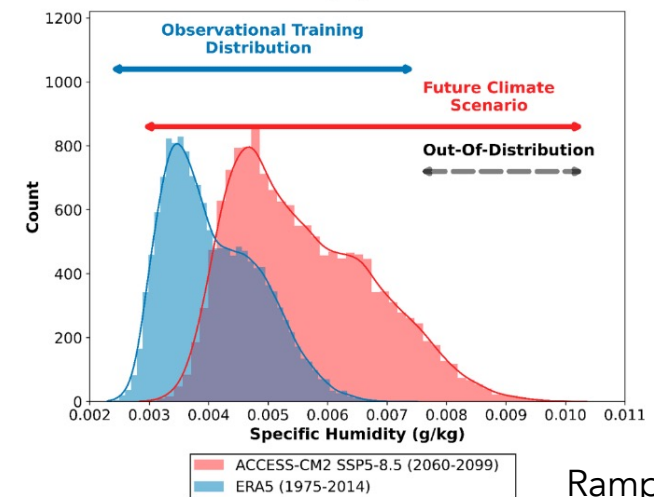
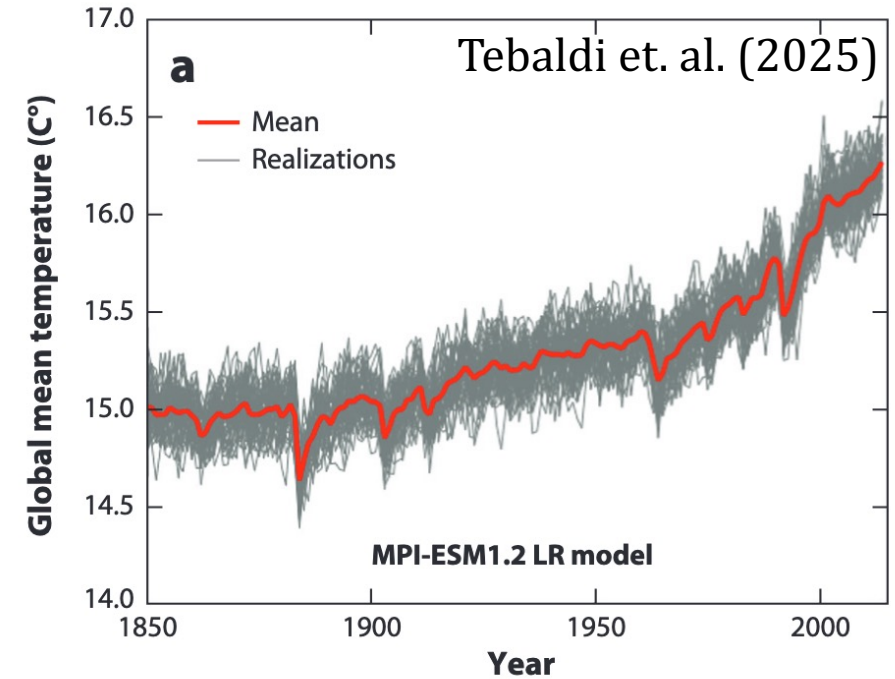


Emulators



Emulators

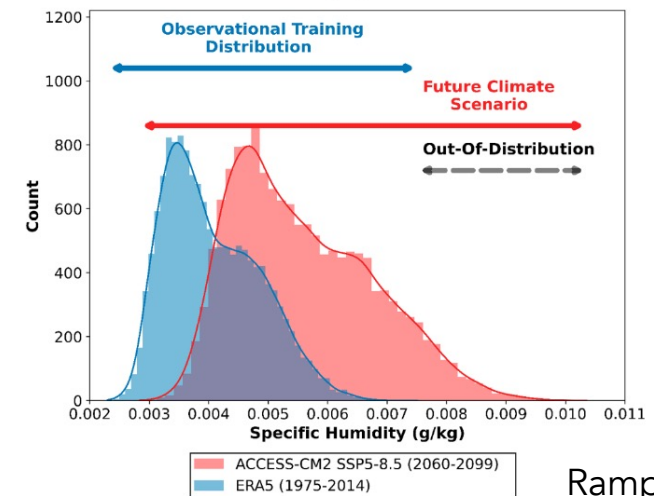
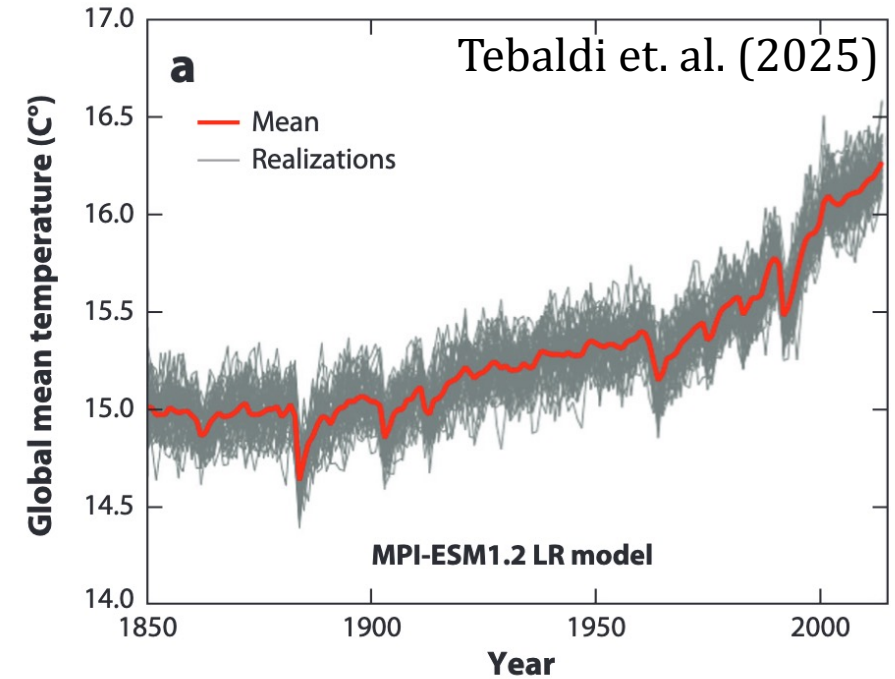
Emulators can substitute for earth system models, and help fill the gap between simulating the physical conditions and the societal need for impact risk



Emulators

Emulators can substitute for earth system models, and help fill the gap between simulating the physical conditions and the societal need for impact risk

Challenges



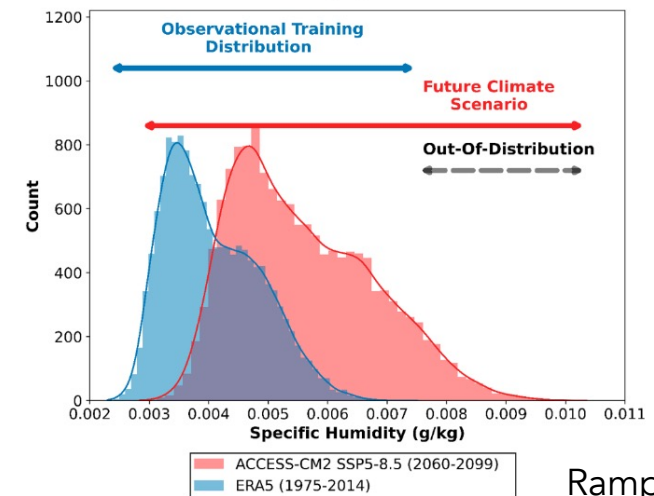
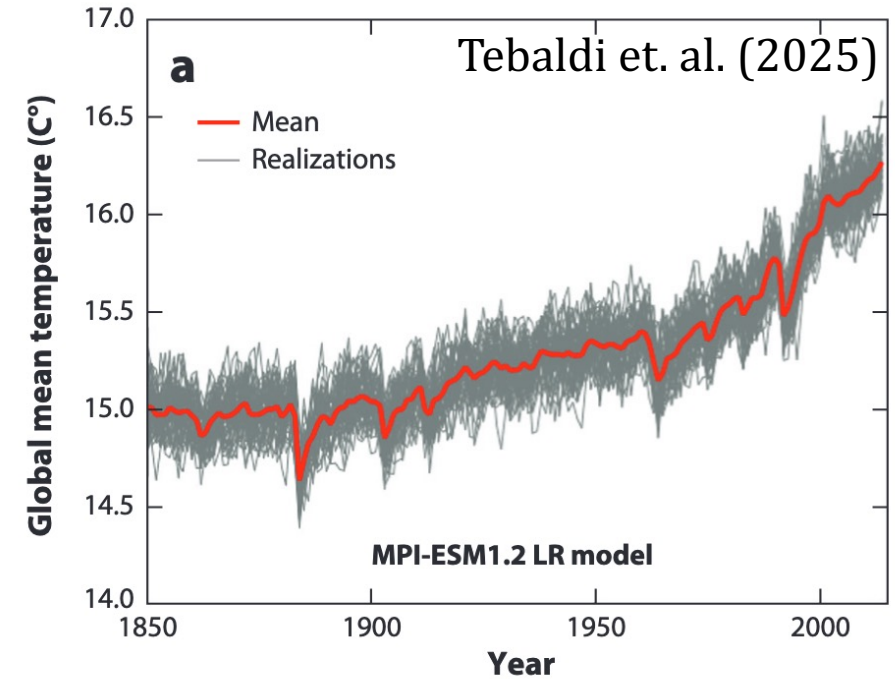
Rampal et al (2024)

Emulators

Emulators can substitute for earth system models, and help fill the gap between simulating the physical conditions and the societal need for impact risk

Challenges

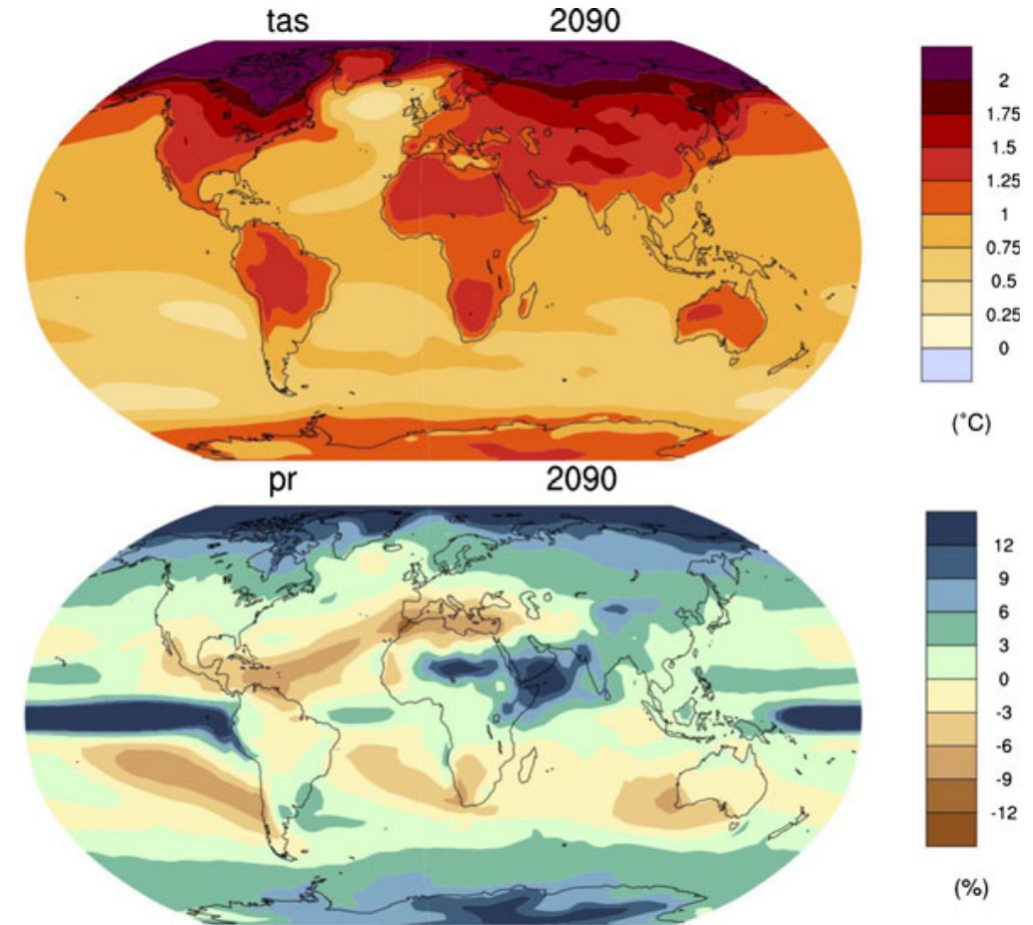
- Requires data from trusted model output
- Needs to be stable over the relevant time period
- Extremes and general circulation patterns should remain physical and realistic



Pattern Scaling

- Changes at each model grid location are a function of change in global temperature.
- Location-specific linear coefficients form scenario- and time-invariant patterns, which are multiplied by a scenario's global temperature outcome.
- Represents only forced change.

$$\mathbf{P}(t, \mathbf{x}, \mathbf{y}, \mathbf{s}) = \mathbf{T}(t) \mathbf{p}(\mathbf{x}, \mathbf{y}, \mathbf{s})$$



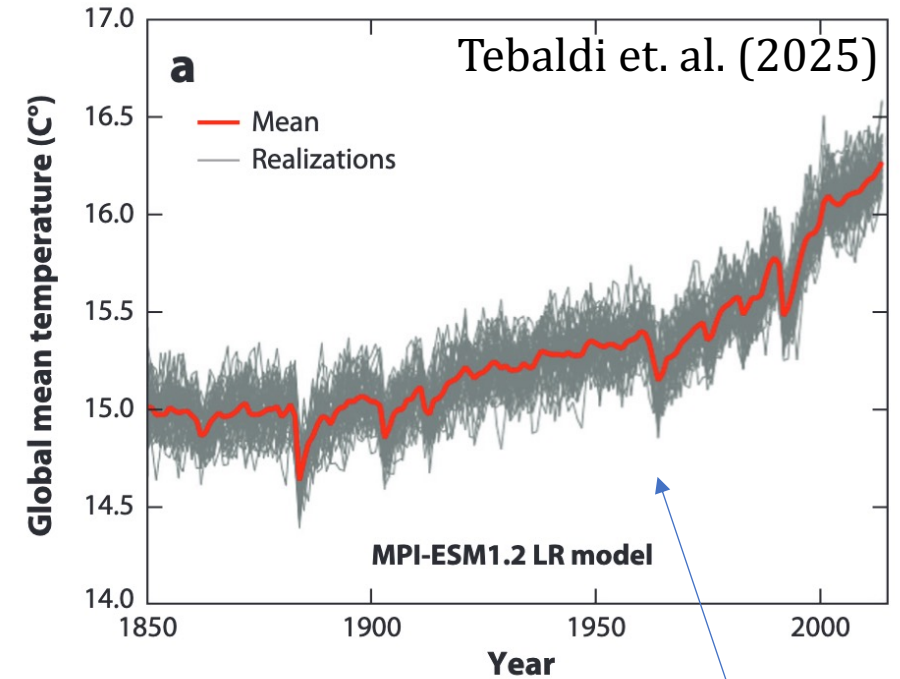
Tebaldi & Arblaster (2015)

Tebaldi et. al. (2025)

Pattern Scaling

- Changes at each model grid location are a function of change in global temperature.
- Location-specific linear coefficients form scenario- and time-invariant patterns, which are multiplied by a scenario's global temperature outcome.
- Represents only forced change.

$$\mathbf{P}(\mathbf{t}, \mathbf{x}, \mathbf{y}, \mathbf{s}) = \mathbf{T}(\mathbf{t}) \mathbf{p}(\mathbf{x}, \mathbf{y}, \mathbf{s})$$



Will only capture the mean
with no internal variability

Tebaldi & Arblaster (2015)

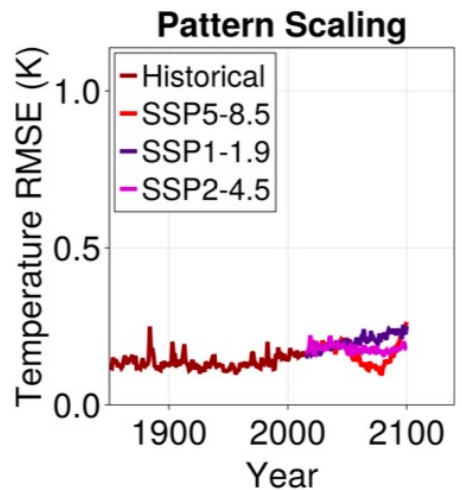
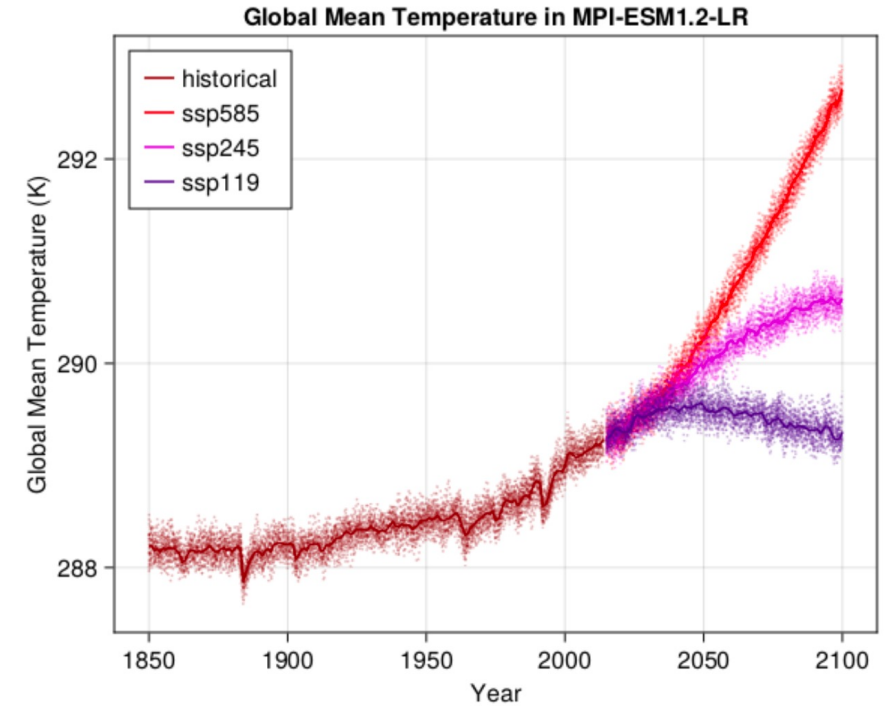
Tebaldi et. al. (2025)

Pattern Scaling

- Extensions add patterns representing additional forcings, timescales, drivers, or simple estimates of internal variability to the forced component.
- Other extensions include noise to account for internal variability, or use nonlinear scaling.

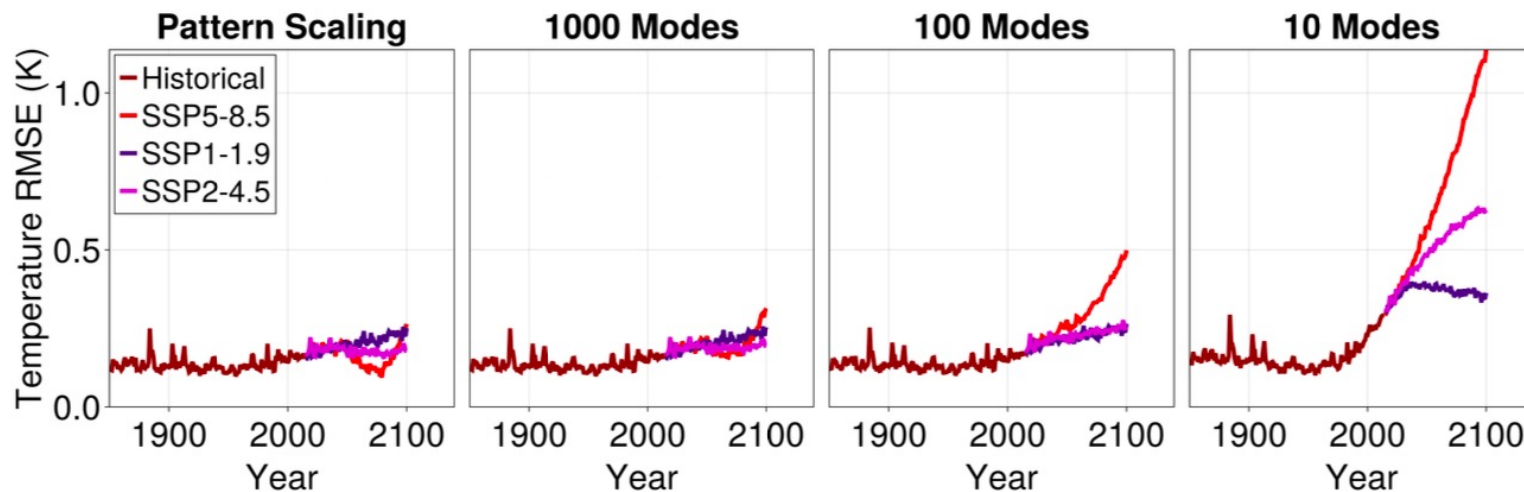
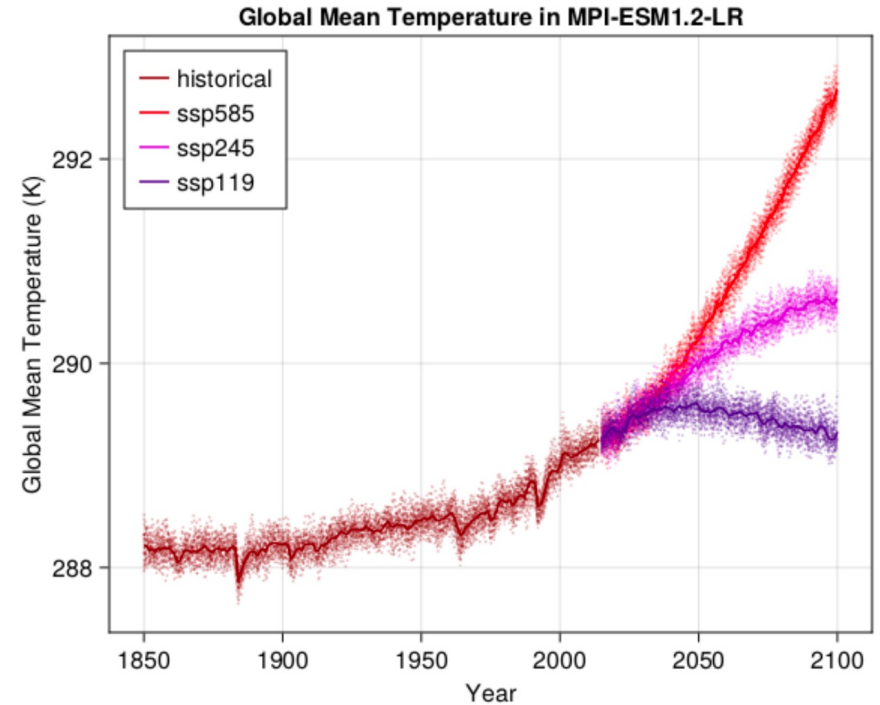
Pattern Scaling

- Example: pattern scaling extension
- Train emulator that predicts distributions of coarse-grained monthly averaged variables as a multivariate Gaussian distribution



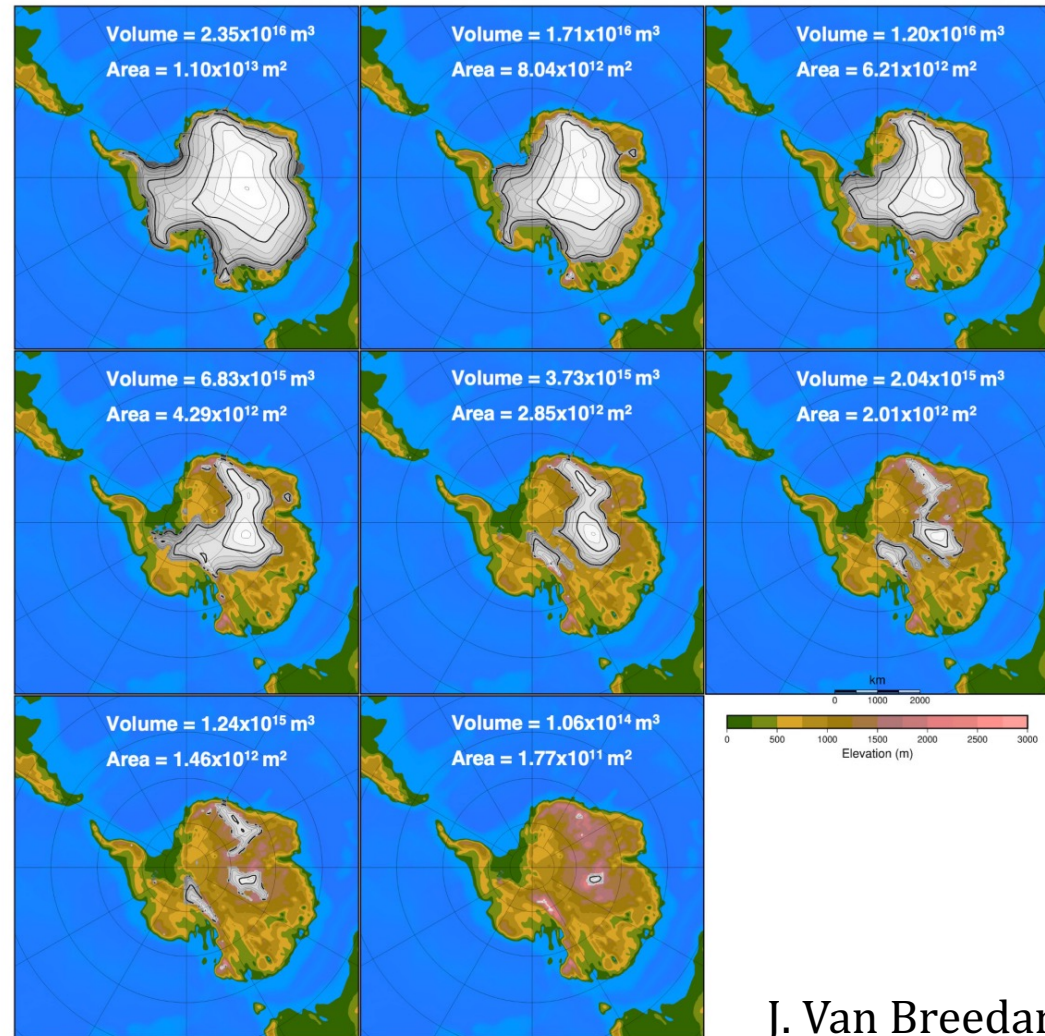
Pattern Scaling

- Example: pattern scaling extension
- Train emulator that predicts distributions of coarse-grained monthly averaged variables as a multivariate Gaussian distribution
- captures regional monthly temperature and relative humidity fields and internal variability



“Light” machine learning applications

- Interested in climate evolution over Antarctica
- Apply Gaussian Process + PCA which considers the response of an ice sheet to changing conditions
- Inputs for GP are ice sheet parameters (thickness, area)
- Outputs are PCAs of climate variables, i.e., maps of temperature, precipitation

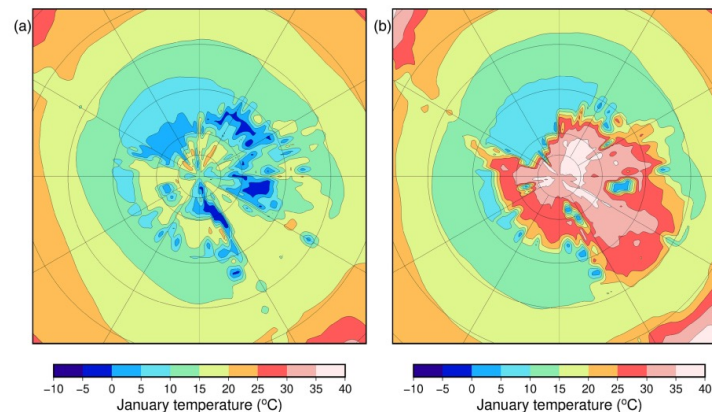
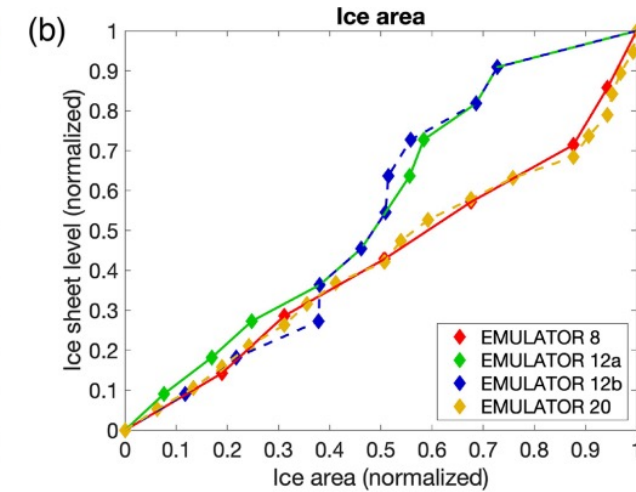
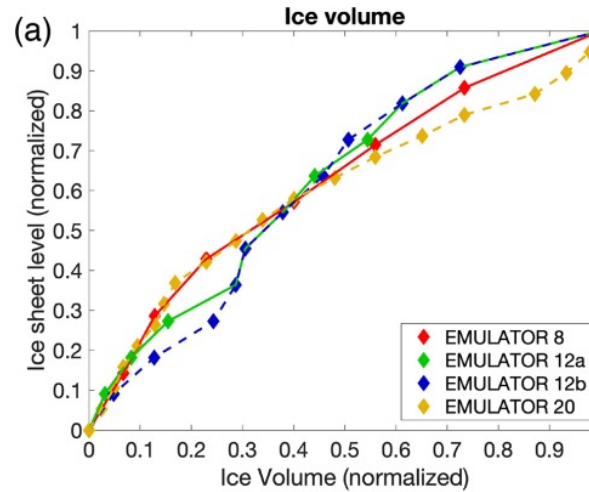


J. Van Breedam et al (2021)

Tebaldi et. al. (2025)

“Light” machine learning applications

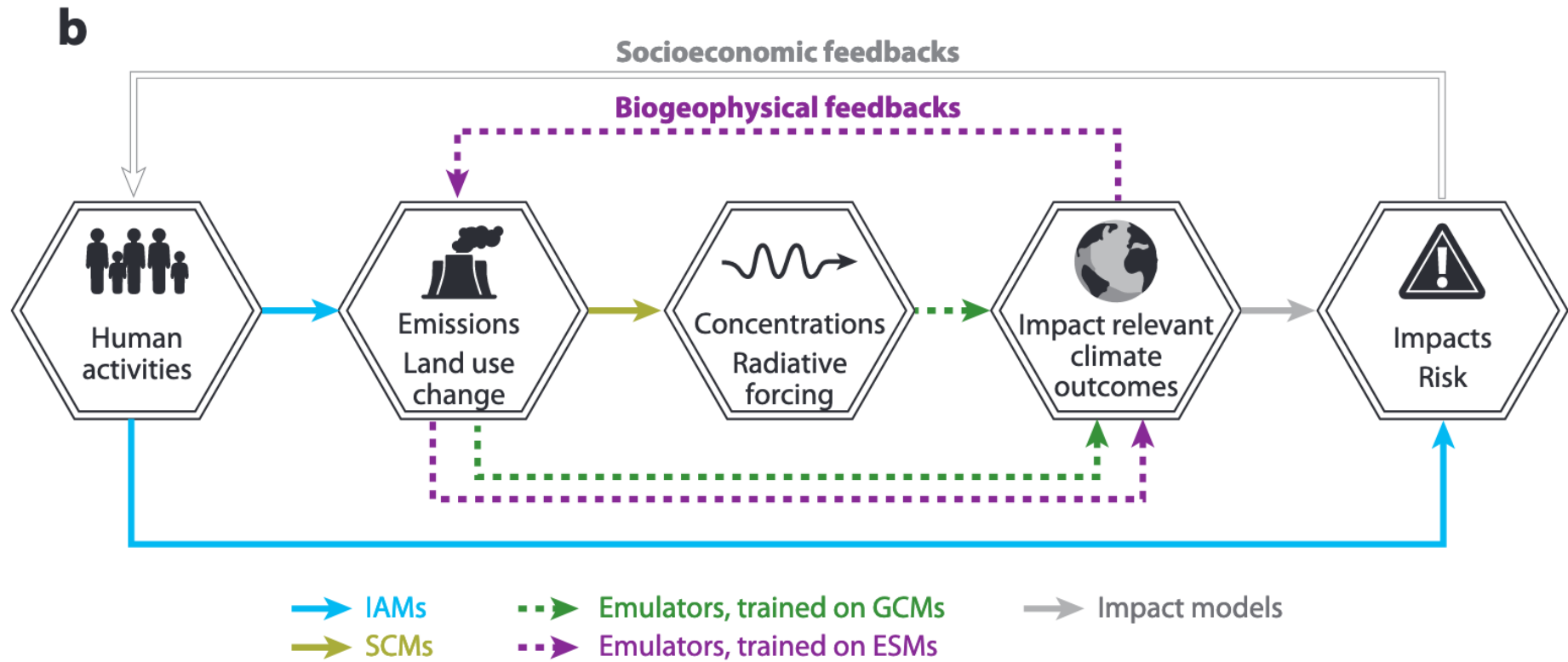
- Interested in climate evolution over Antarctica
- Apply Gaussian Process + PCA which considers the response of an ice sheet to changing conditions
- Inputs for GP are ice sheet parameters (thickness, area)
- Outputs are PCAs of climate variables, i.e., maps of temperature, precipitation



J. Van Breedam et al (2021)

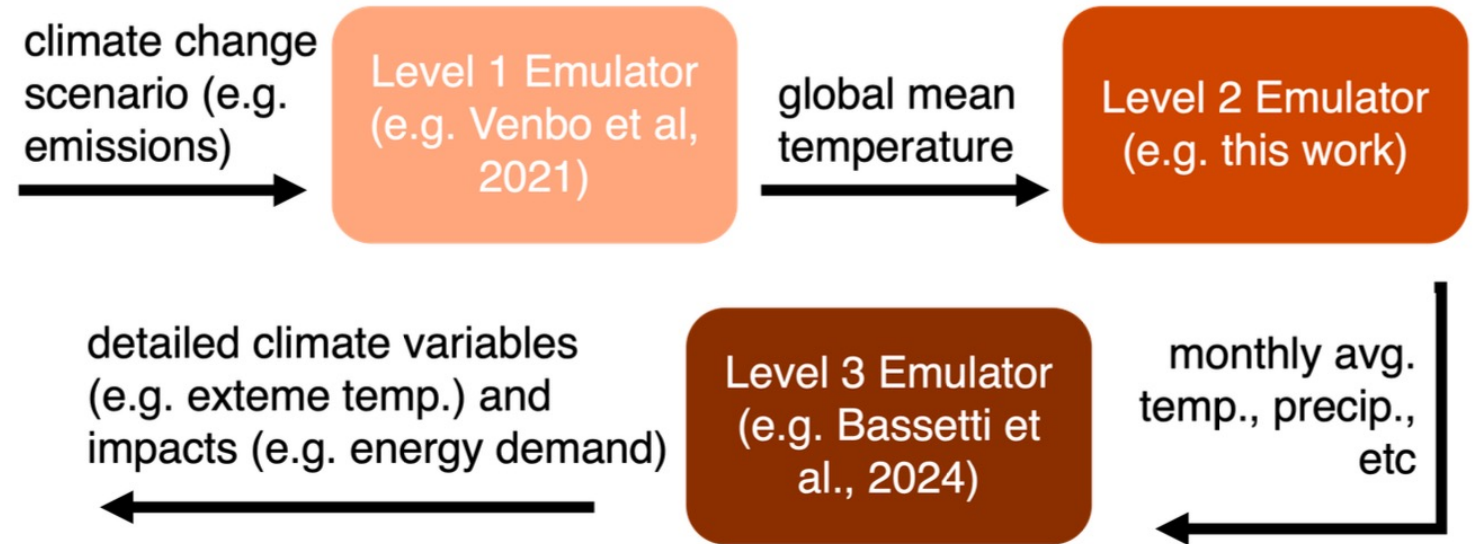
Tebaldi et. al. (2025)

AI Emulators



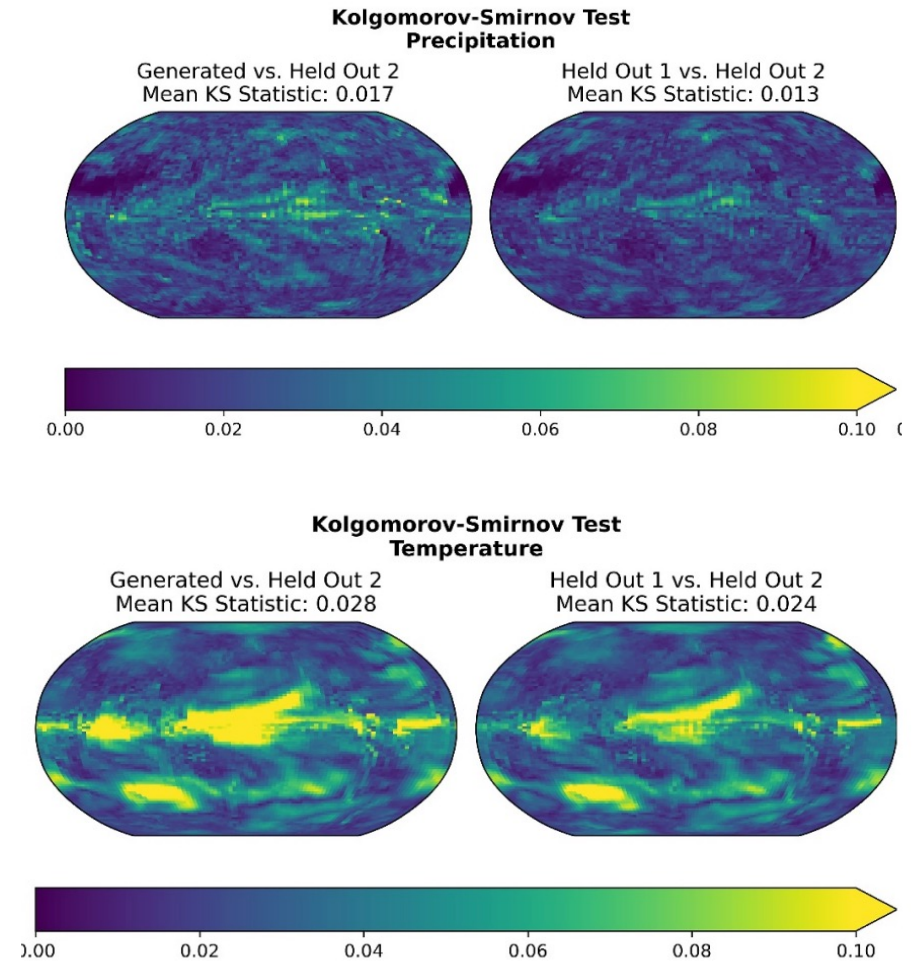
Example: DiffESM

- Takes monthly climate data of temperature, precipitation
- Generates realistic daily sequences using diffusion models



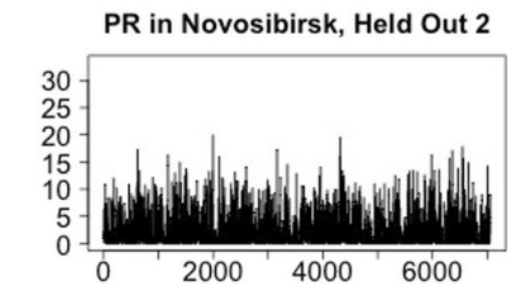
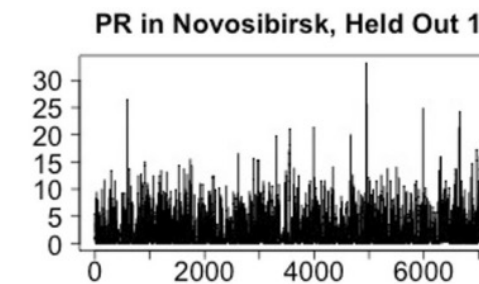
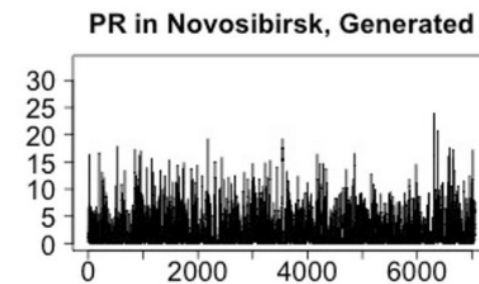
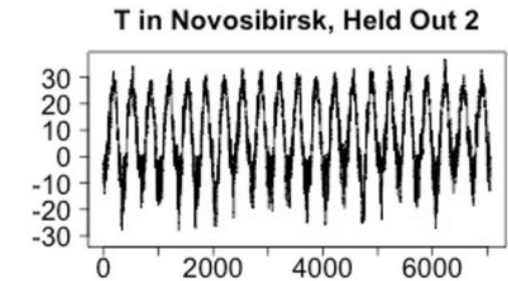
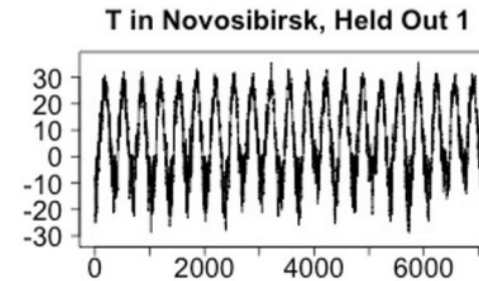
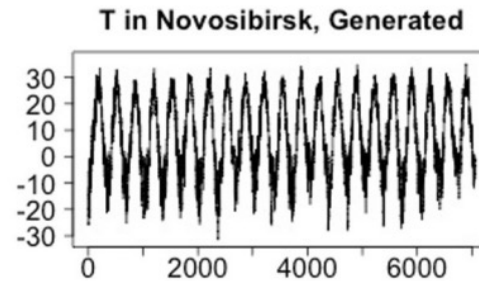
Example: DiffESM

- Takes monthly climate data of temperature, precipitation
- Generates realistic daily sequences using diffusion models
- The diffusion model is able to preserve the overall statistics of daily temperature and precipitation



Example: DiffESM

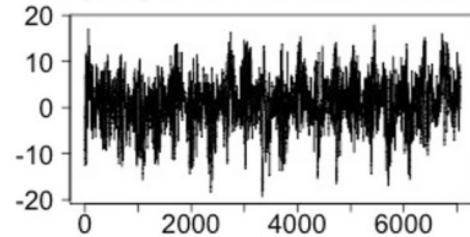
- Takes monthly climate data of temperature, precipitation
- Generates realistic daily sequences using diffusion models
- The model is able to preserve the overall statistics of daily temperature and precipitation



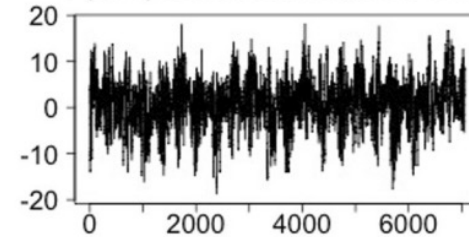
Example: DiffESM

- Takes monthly climate data of temperature, precipitation
- Generates realistic daily sequences using diffusion models
- The model is able to preserve the overall statistics of daily temperature and precipitation
- The model is not sensitive to the seasonal cycle

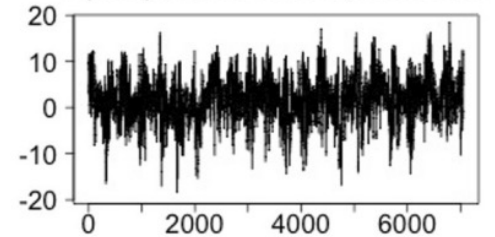
T (des.) in Novosibirsk, Generated



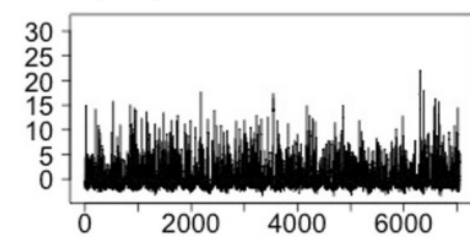
T (des.) in Novosibirsk, Held Out 1



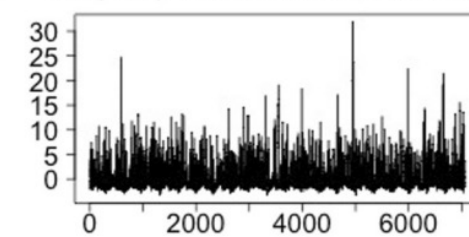
T (des.) in Novosibirsk, Held Out 2



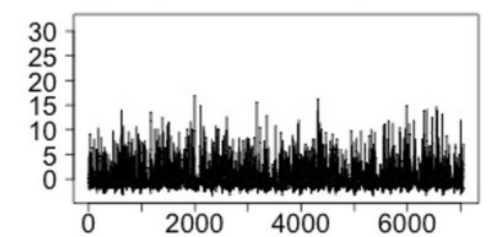
PR (des.) in Novosibirsk, Generated



PR (des.) in Novosibirsk, Held Out 1

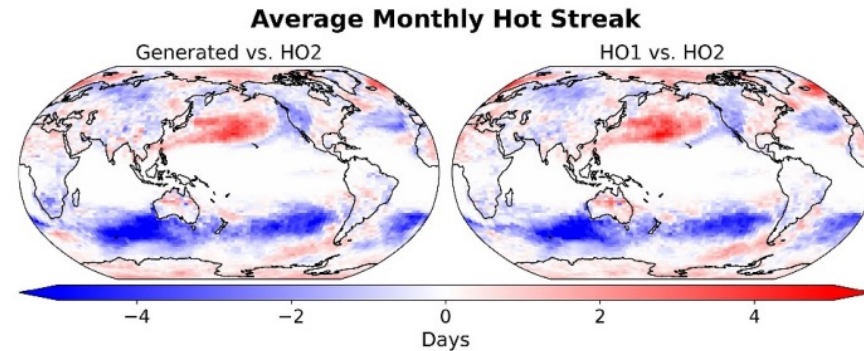
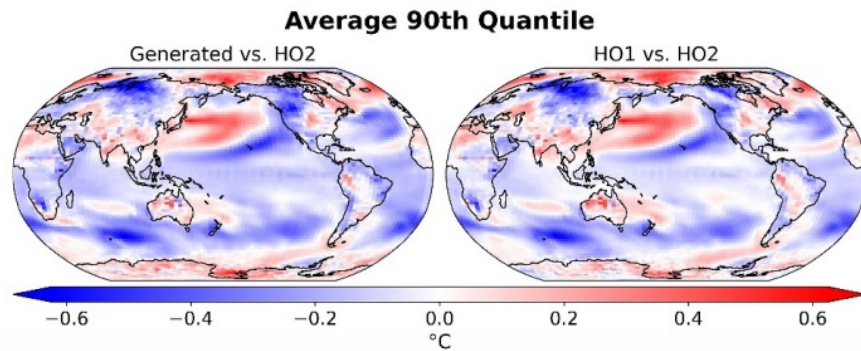
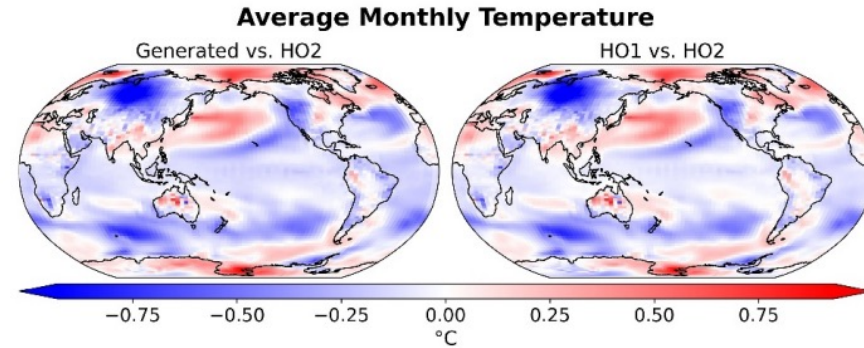
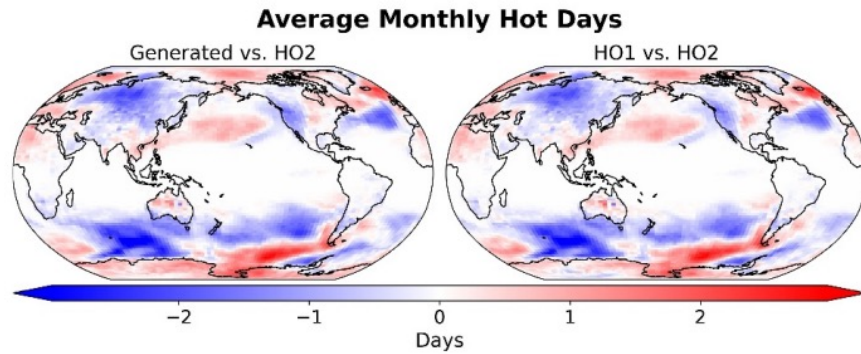


PR (des.) in Novosibirsk, Held Out 2



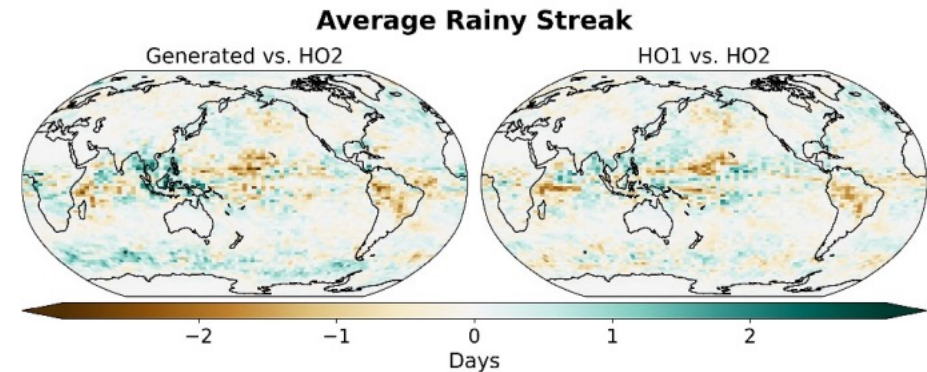
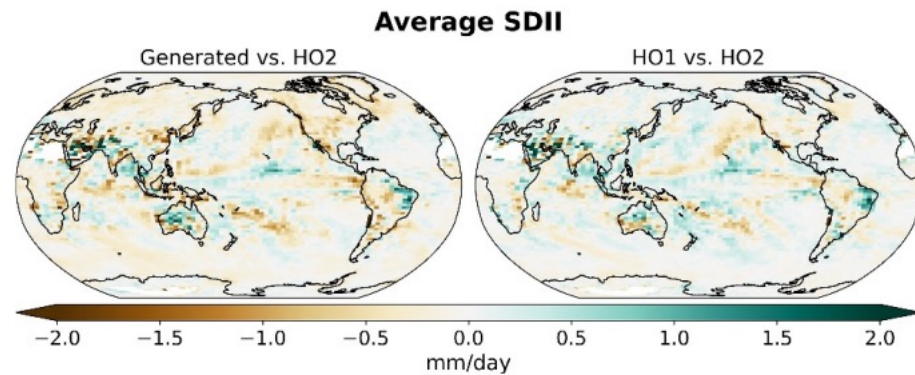
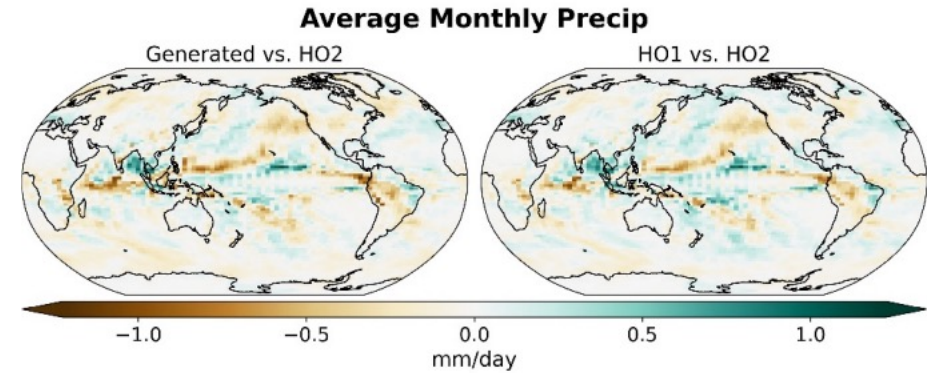
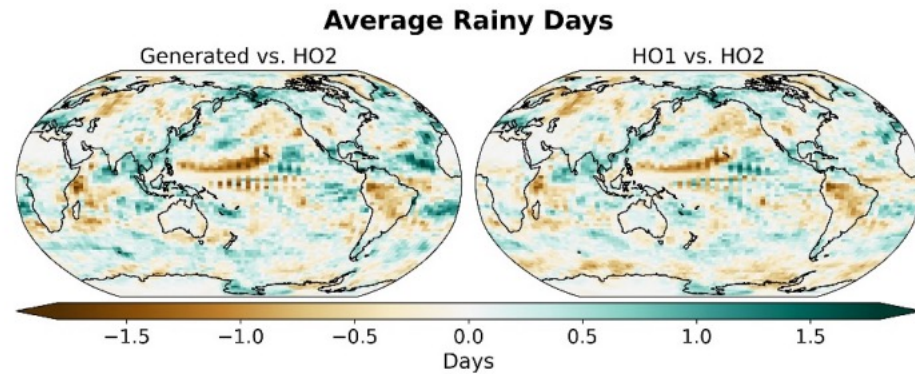
Example: DiffESM

RCP 8.5



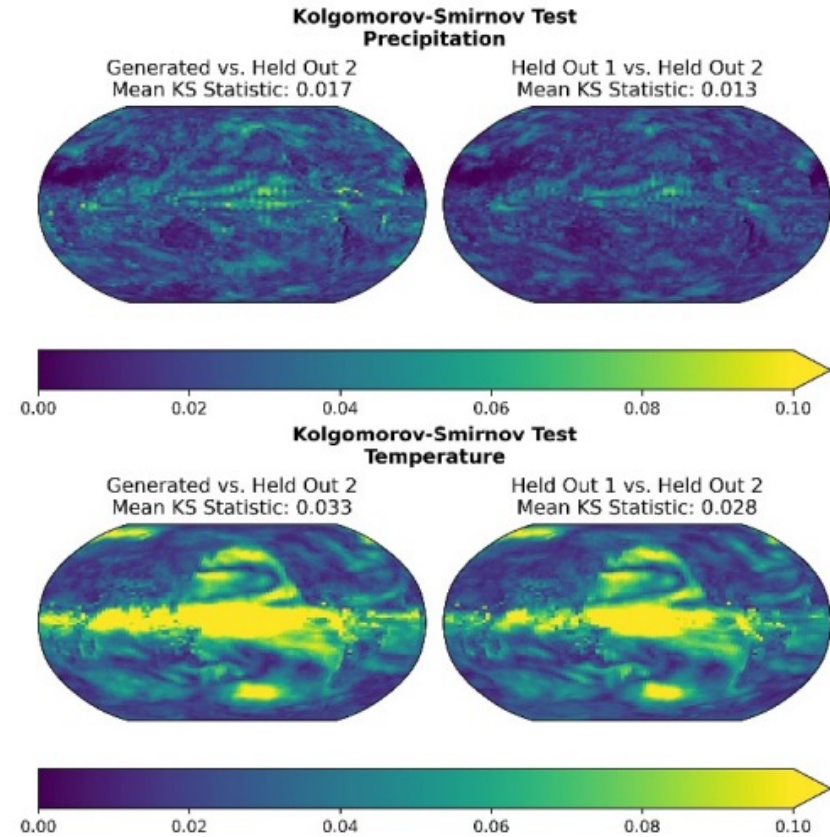
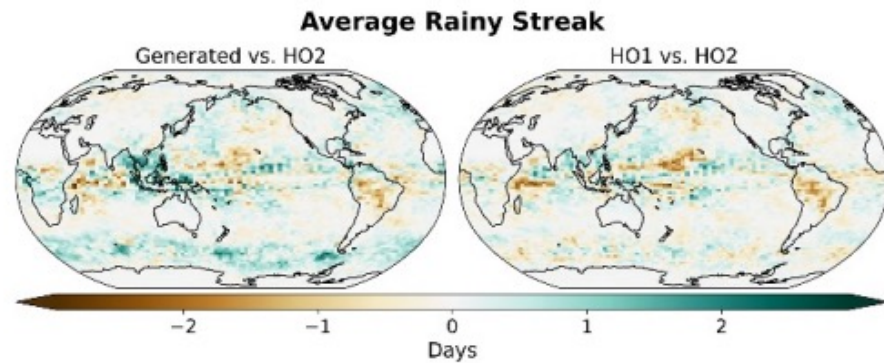
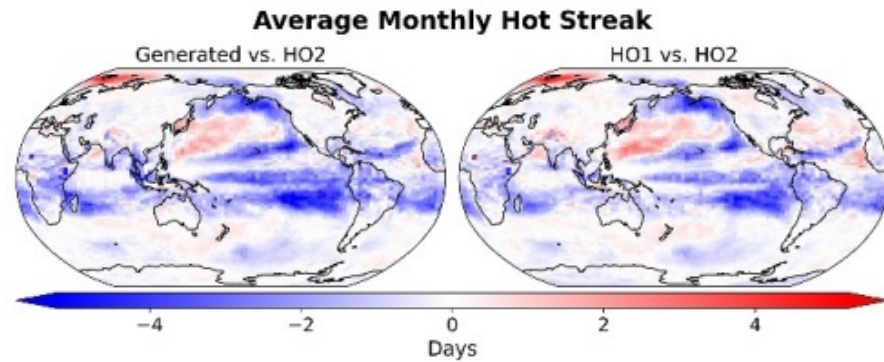
Example: DiffESM

RCP 8.5



Example: DiffESM

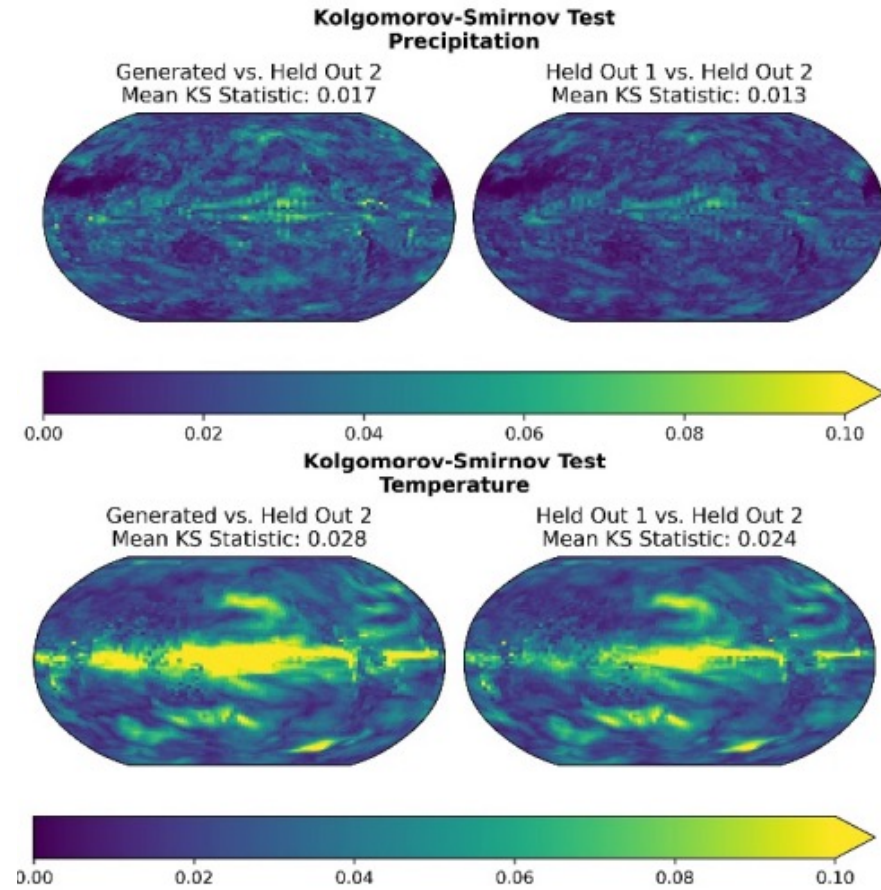
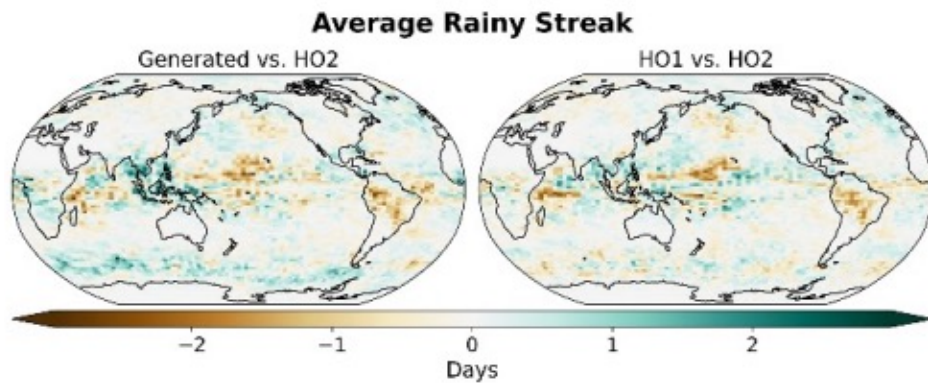
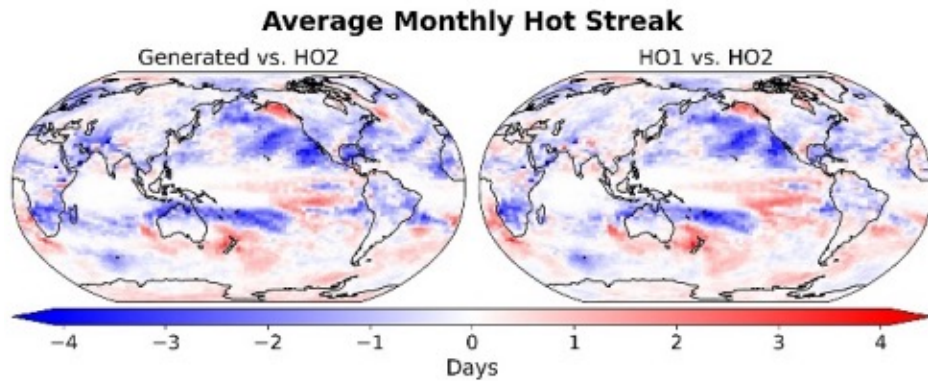
RCP2.6



The model is able to generalize onto other RCP scenarios

Example: DiffESM

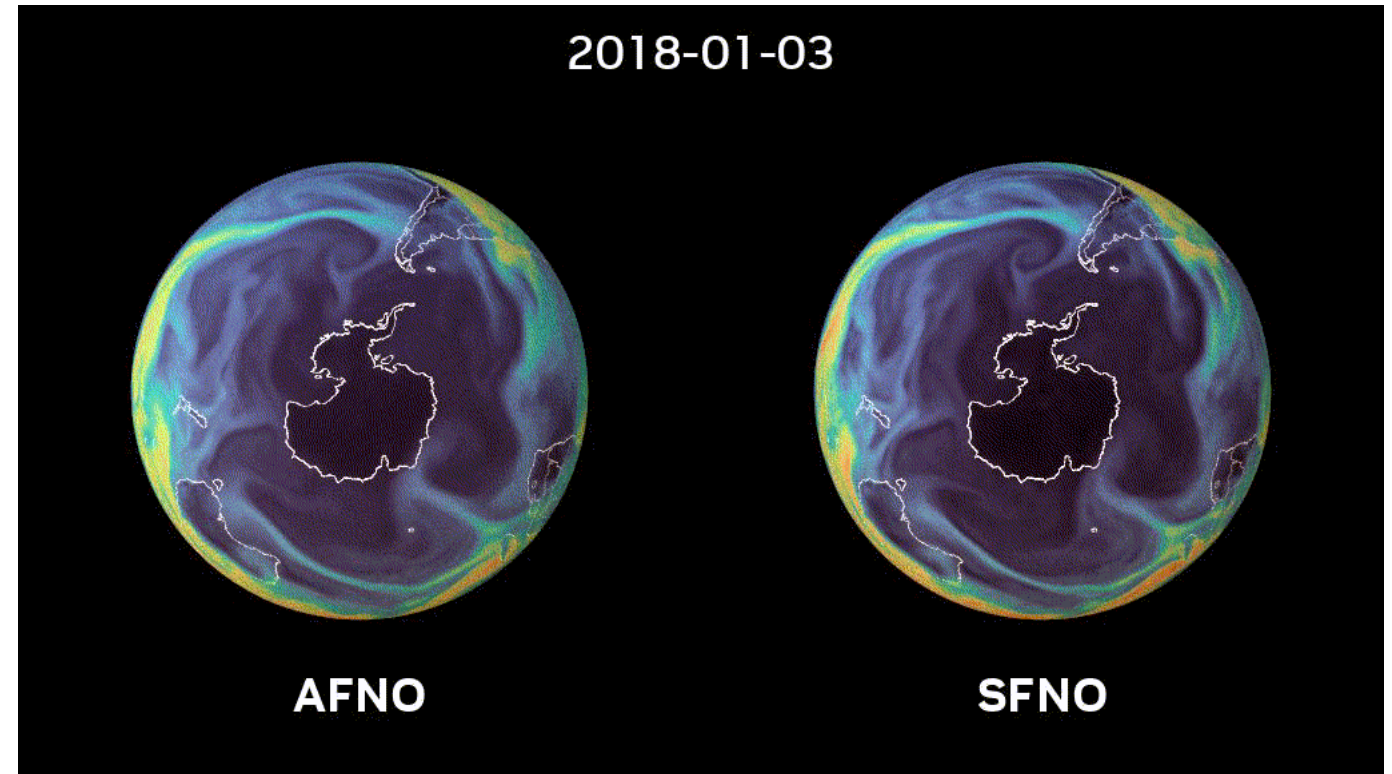
RCP4.5



The model is able to generalize onto other RCP scenarios

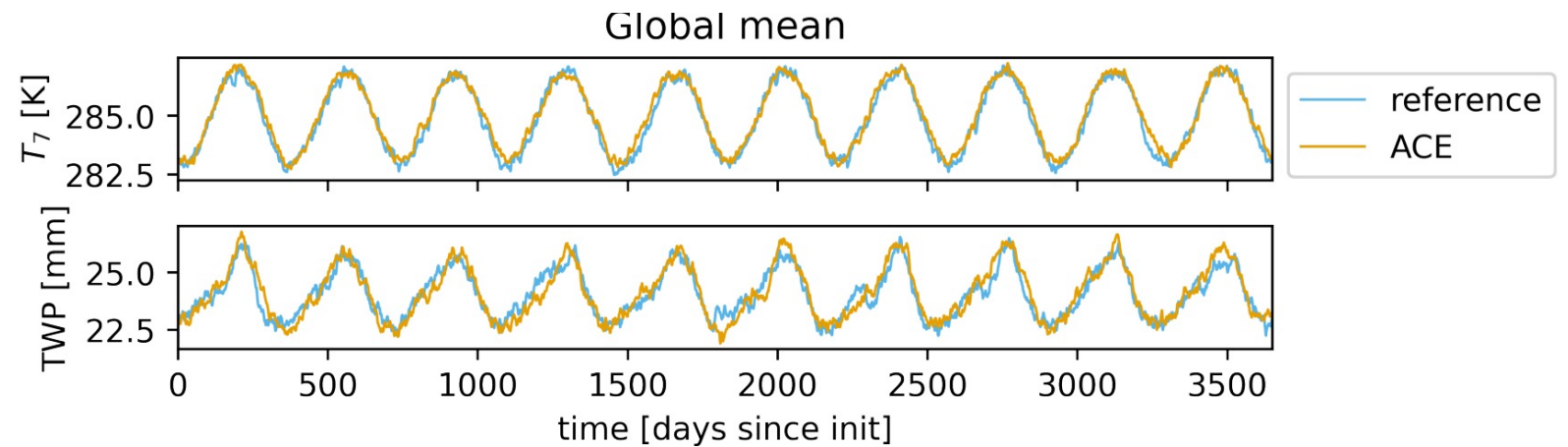
ACE: AI2 Climate Emulator

- Adapted Nvidia's spherical Fourier neural operators approach for long climate rollouts



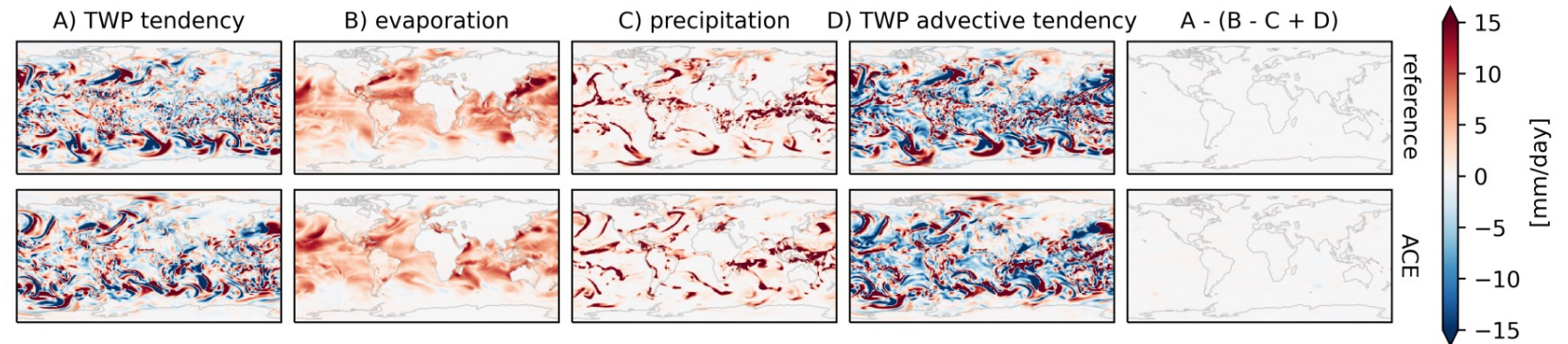
ACE: AI2 Climate Emulator

- Adapted Nvidia's spherical Fourier neural operators approach for long climate rollouts
- Trained on 10 years of global atmospheric model output (not ERA5 like most data assimilation / weather prediction tools)

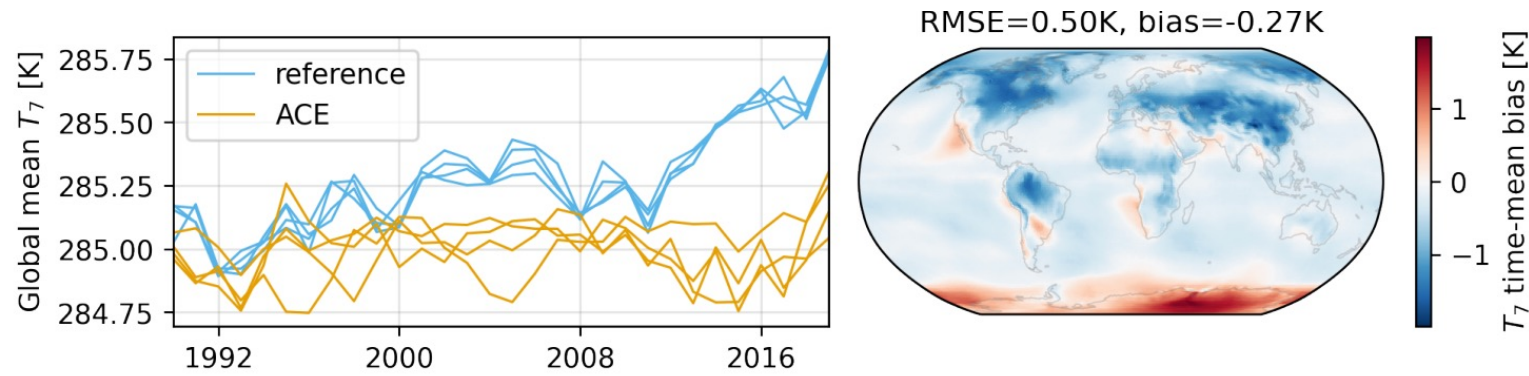


ACE: AI2 Climate Emulator

- Adapted Nvidia's spherical Fourier neural operators approach for long climate rollouts
- Trained on 10 years of global atmospheric model output (not ERA5 like most data assimilation / weather prediction tools)
- Runs stably for 100 years
- Water budget terms remain close to ensemble mean from 11 members of global atmospheric models

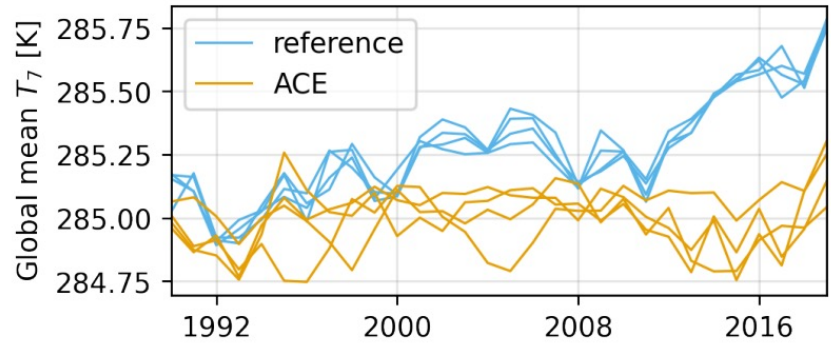


ACE: AI2 Climate Emulator

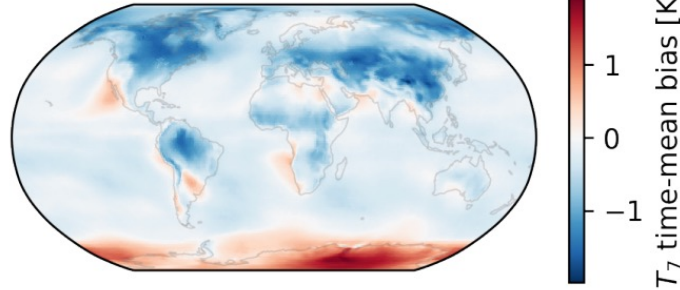


- However, is not able to capture trends in temperature changes

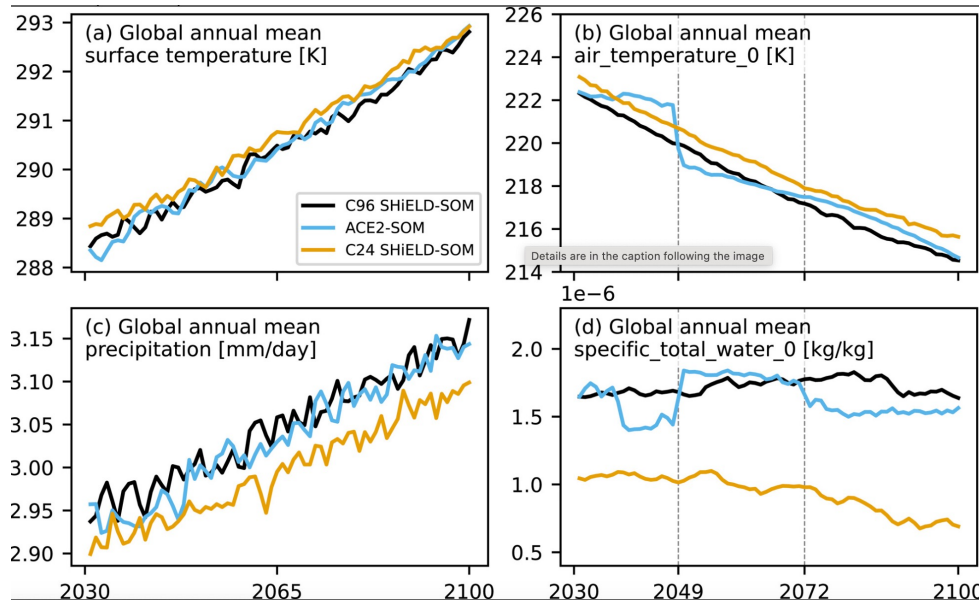
ACE-SOM (slab ocean model)



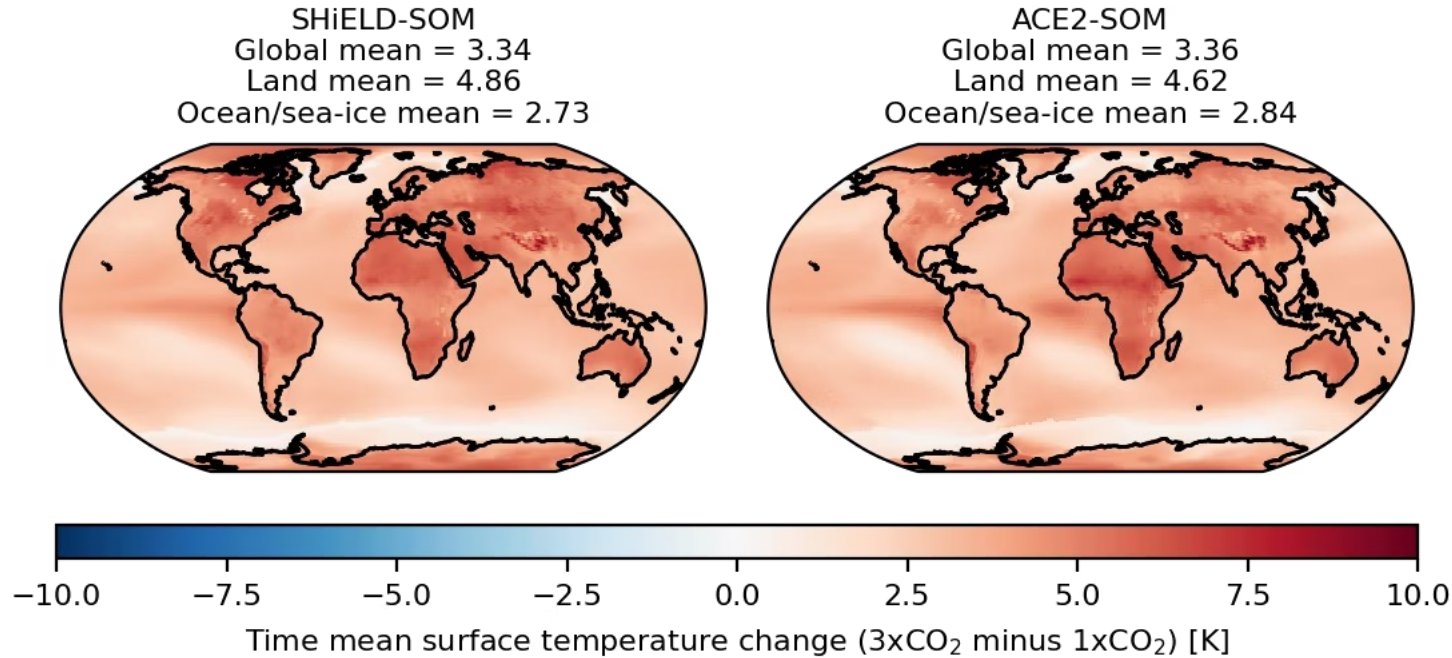
RMSE=0.50K, bias=-0.27K



- However, is not able to capture trends in temperature changes
- A follow-up study with ocean forcing is able to correct for the trend

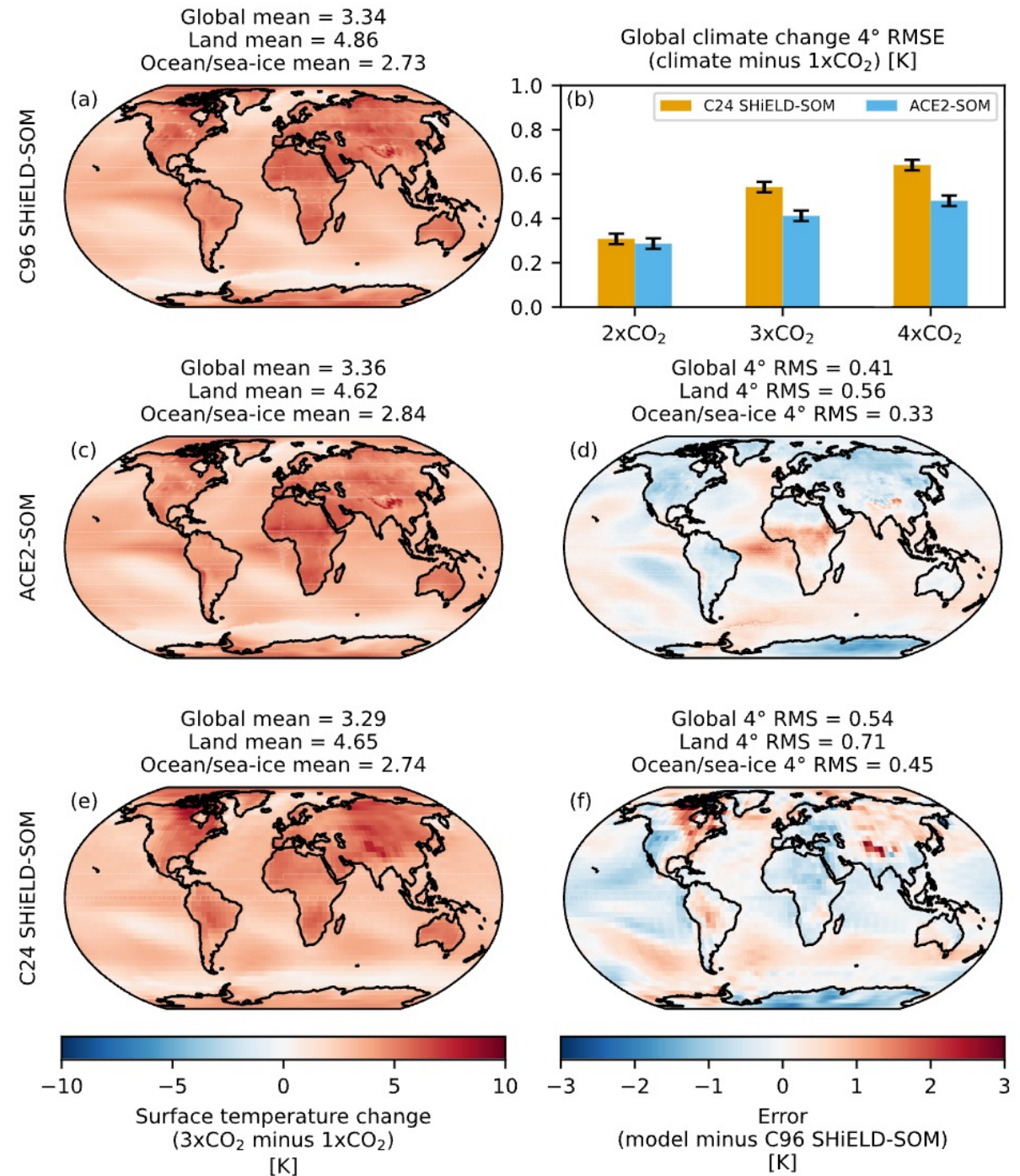


ACE-SOM (slab ocean model)

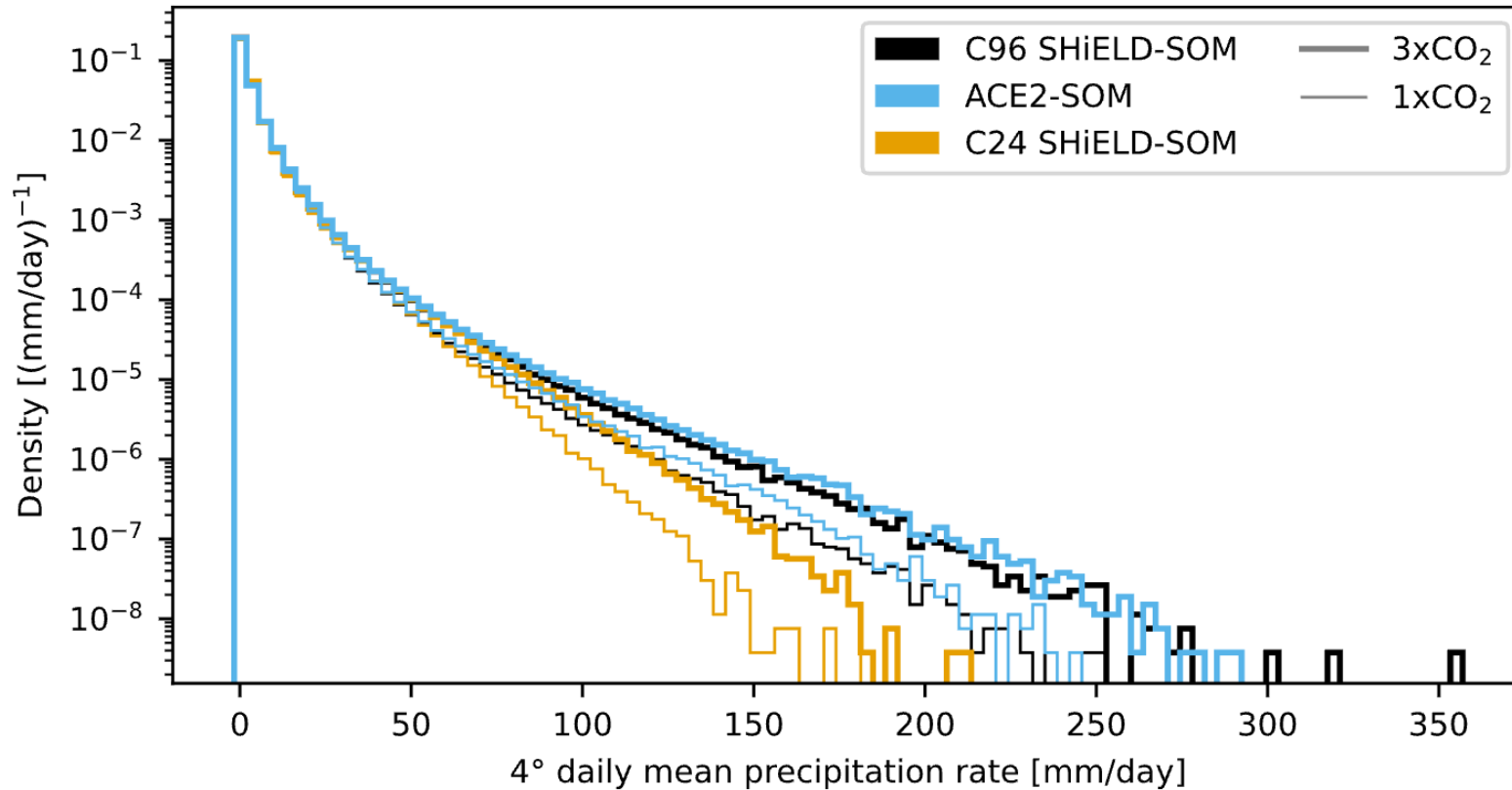


ACE-SOM (slab ocean model)

- ACE-SOM has skill over different climate change scenarios.



ACE-SOM (slab ocean model)



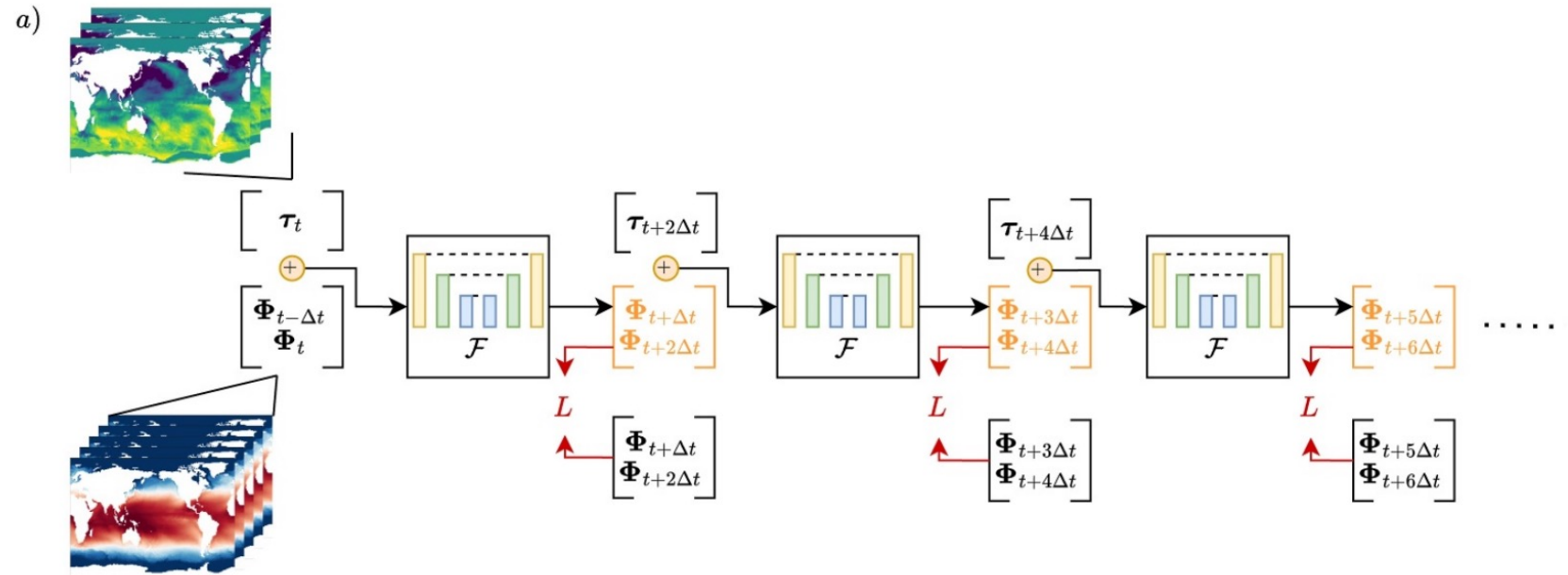
Samudra: Autoregressive AI ocean emulator

$$\tilde{\Phi}_{t+(n+1)\Delta t}, \tilde{\Phi}_{t+(n+2)\Delta t} = \mathcal{F}(\tilde{\Phi}_{t+(n-1)\Delta t}, \tilde{\Phi}_{t+n\Delta t}, \tau_{t+n\Delta t})$$

$$\Phi_{\text{thermo}} = (\theta_O, S, SSH)$$

$$\Phi_{\text{dynamic}} = (u, v)$$

$$\tau = (\tau_u, \tau_v, Q, Q_{anom})$$



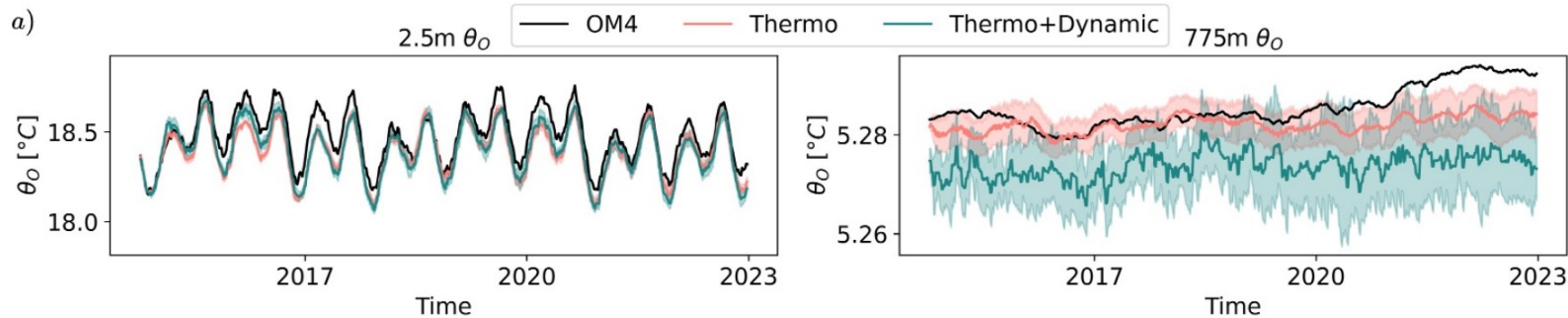
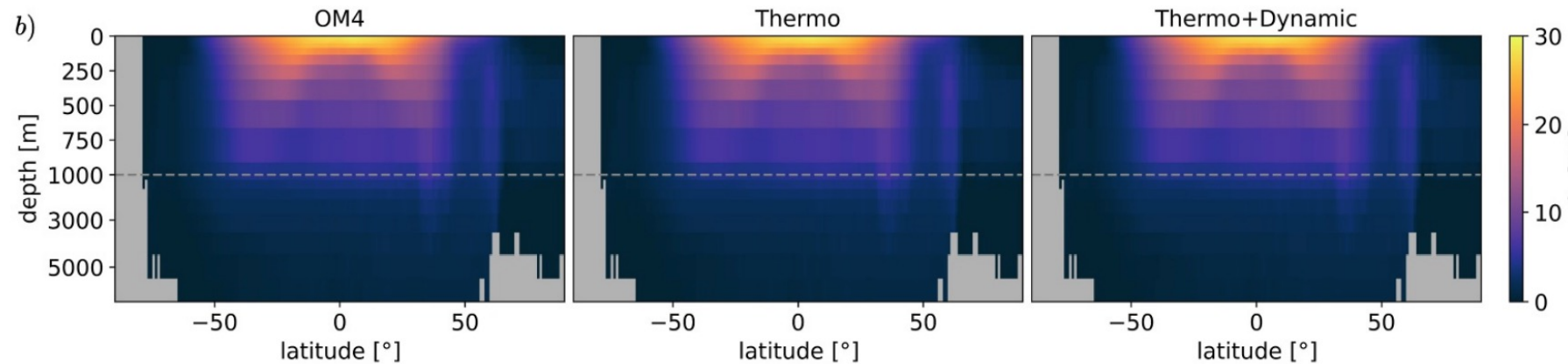
Samudra: Autoregressive AI ocean emulator

$$\tilde{\Phi}_{t+(n+1)\Delta t}, \tilde{\Phi}_{t+(n+2)\Delta t} = \mathcal{F}(\tilde{\Phi}_{t+(n-1)\Delta t}, \tilde{\Phi}_{t+n\Delta t}, \tau_{t+n\Delta t})$$

$$\Phi_{\text{thermo}} = (\theta_o, S, SSH)$$

$$\Phi_{\text{dynamic}} = (u, v)$$

$$\tau = (\tau_u, \tau_v, Q, Q_{anom})$$



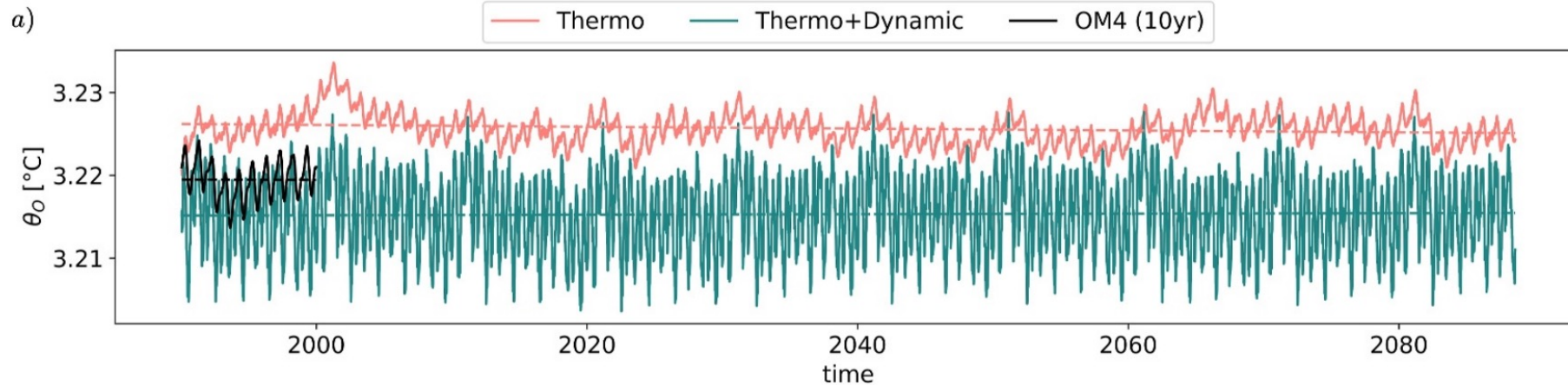
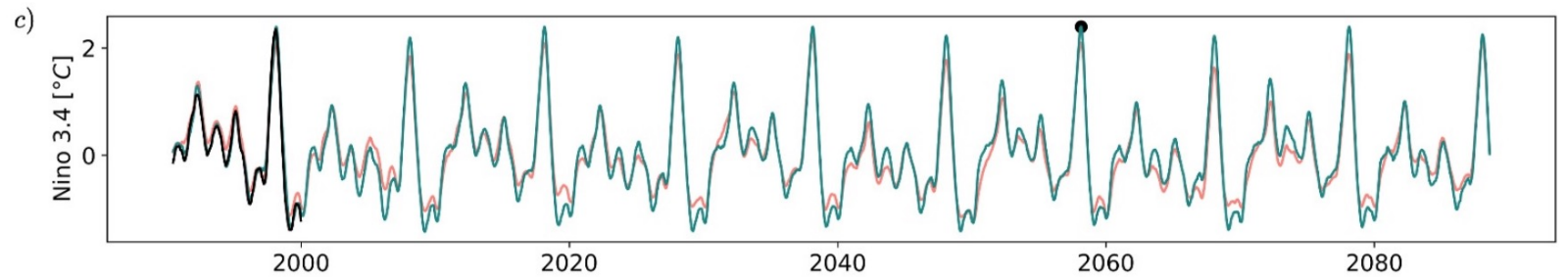
Samudra: Autoregressive AI ocean emulator

$$\tilde{\Phi}_{t+(n+1)\Delta t}, \tilde{\Phi}_{t+(n+2)\Delta t} = \mathcal{F}(\tilde{\Phi}_{t+(n-1)\Delta t}, \tilde{\Phi}_{t+n\Delta t}, \boldsymbol{\tau}_{t+n\Delta t})$$

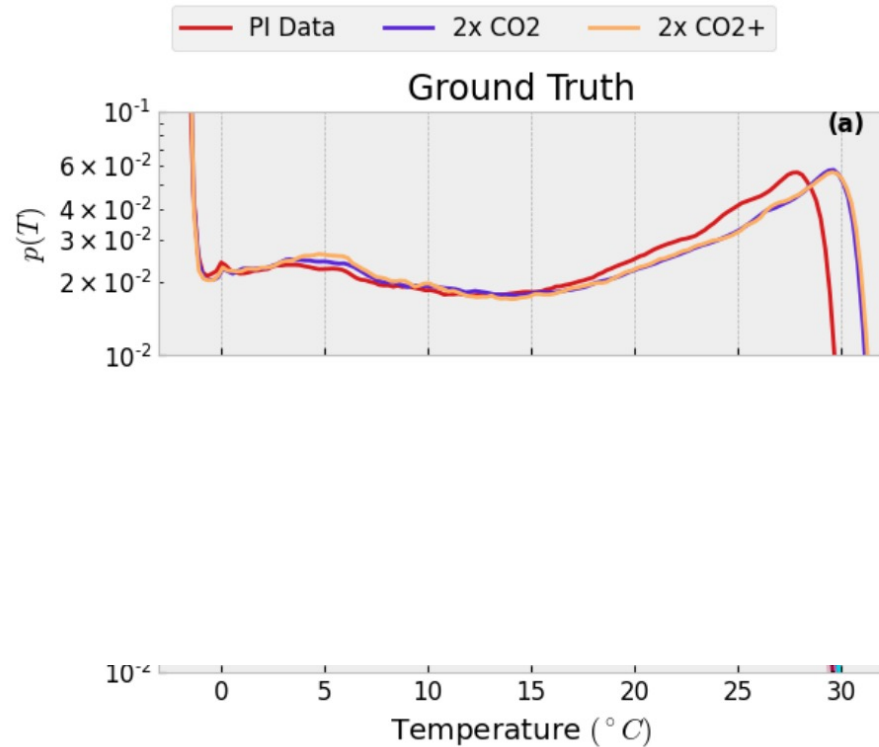
$$\Phi_{\text{thermo}} = (\theta_O, S, SSH)$$

$$\Phi_{\text{dynamic}} = (u, v)$$

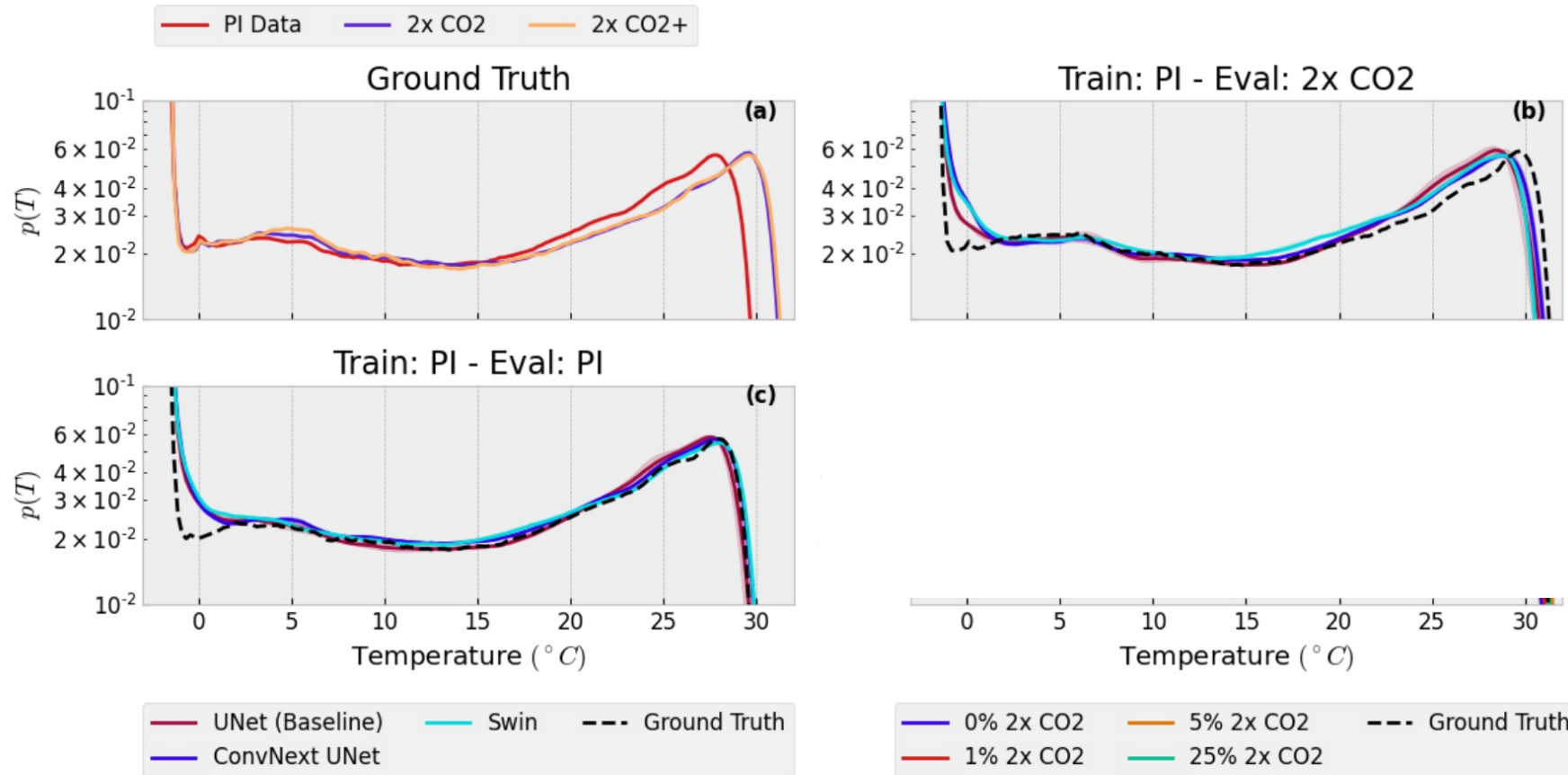
$$\boldsymbol{\tau} = (\tau_u, \tau_v, Q, Q_{\text{anom}})$$



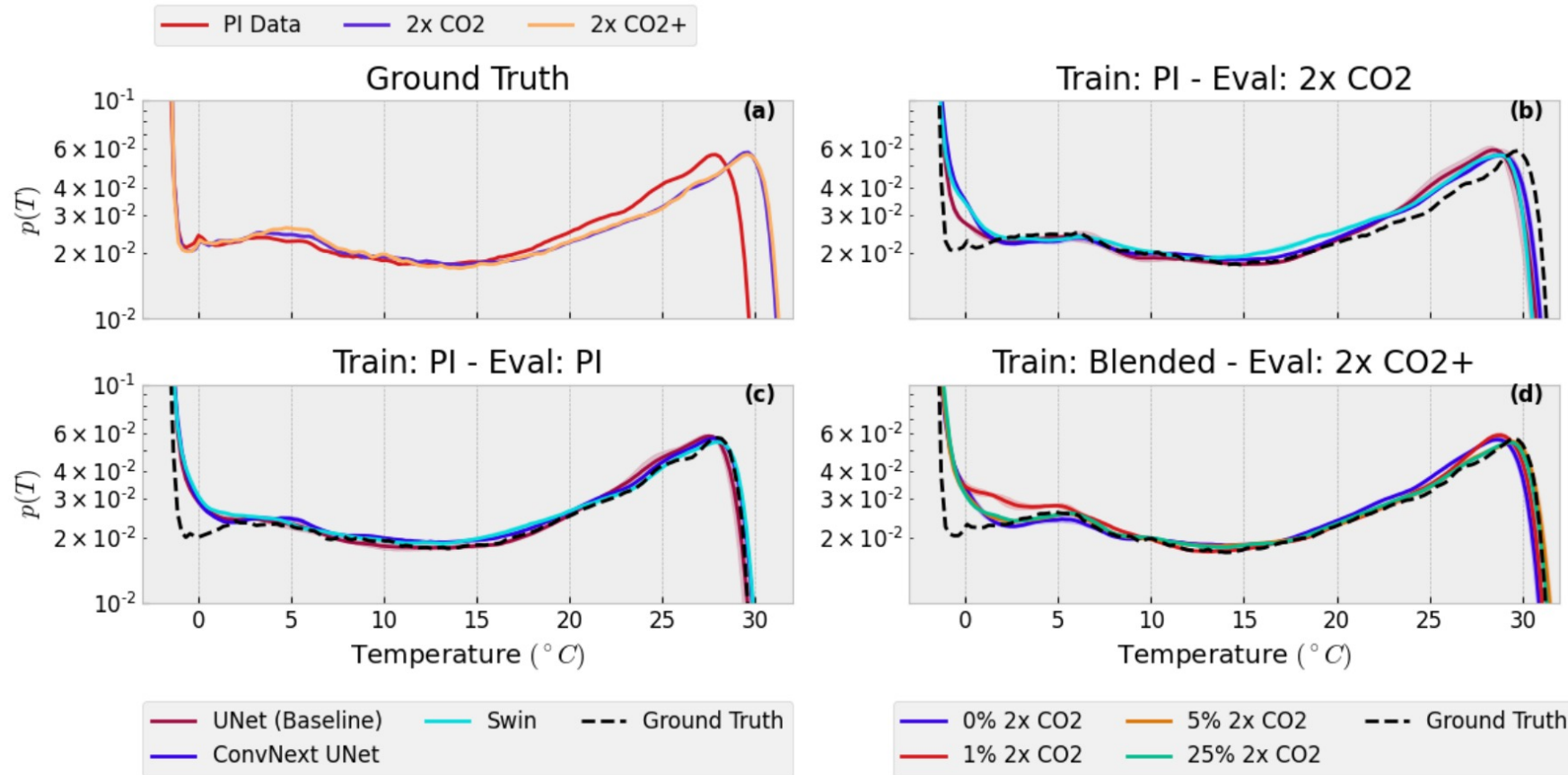
Samudra: Autoregressive AI ocean emulator



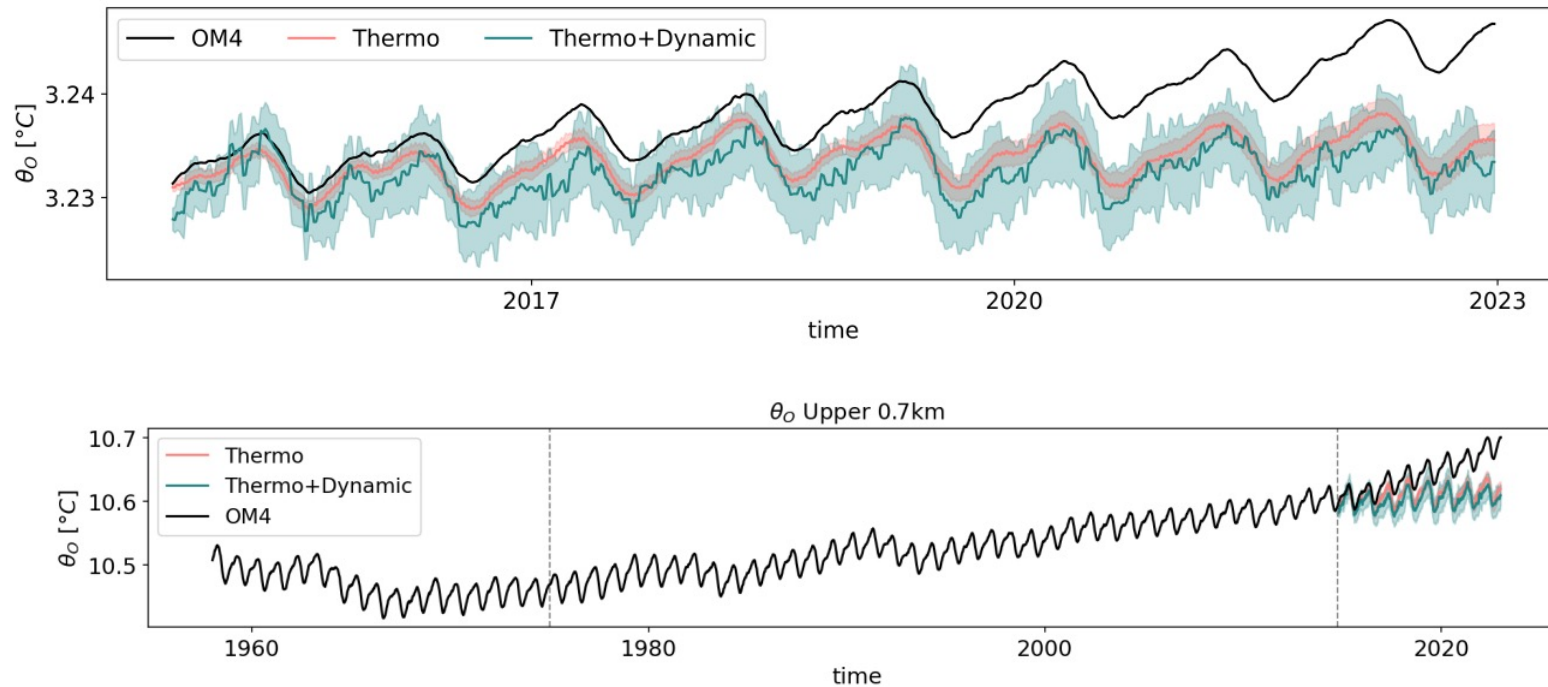
Samudra: Autoregressive AI ocean emulator



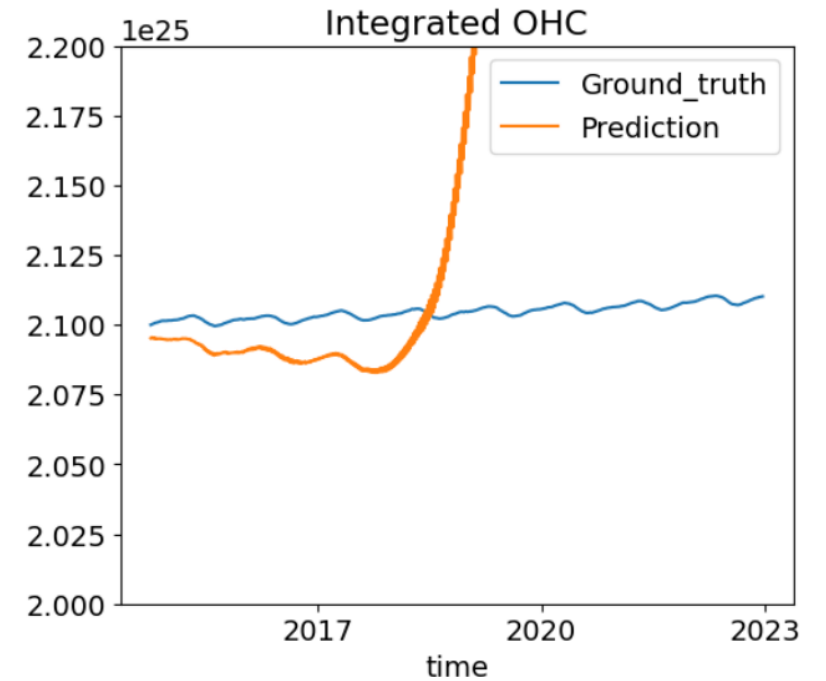
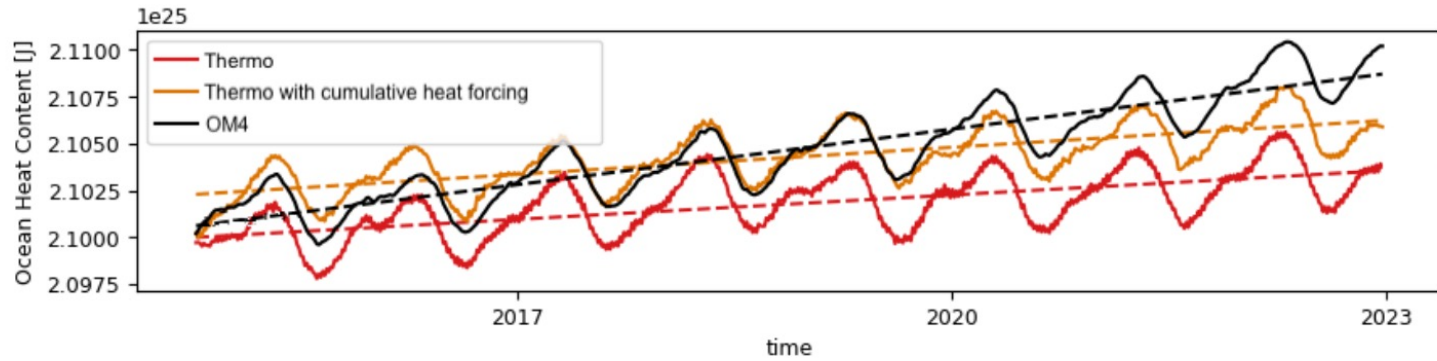
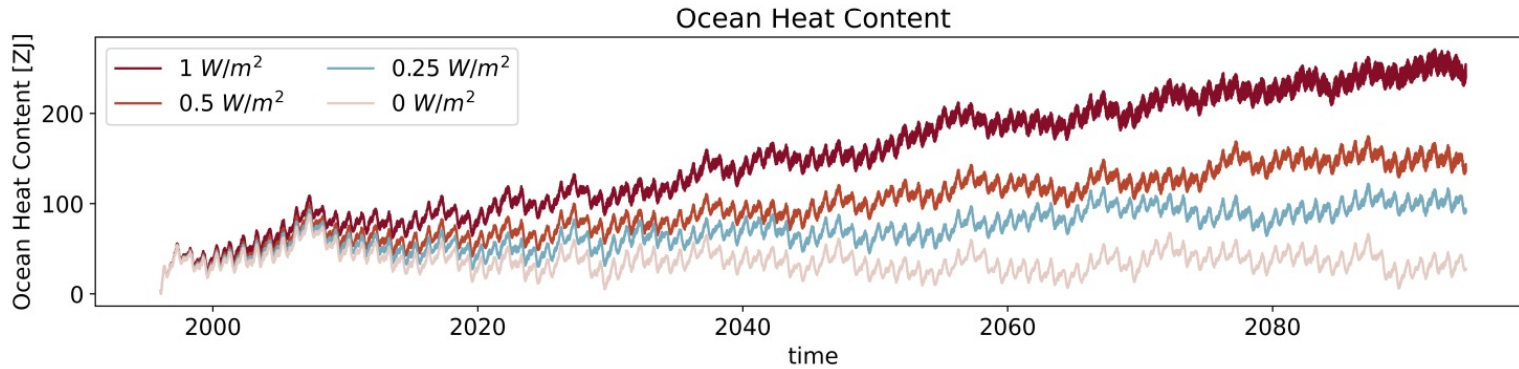
Samudra: Autoregressive AI ocean emulator



Samudra: Autoregressive AI ocean emulator

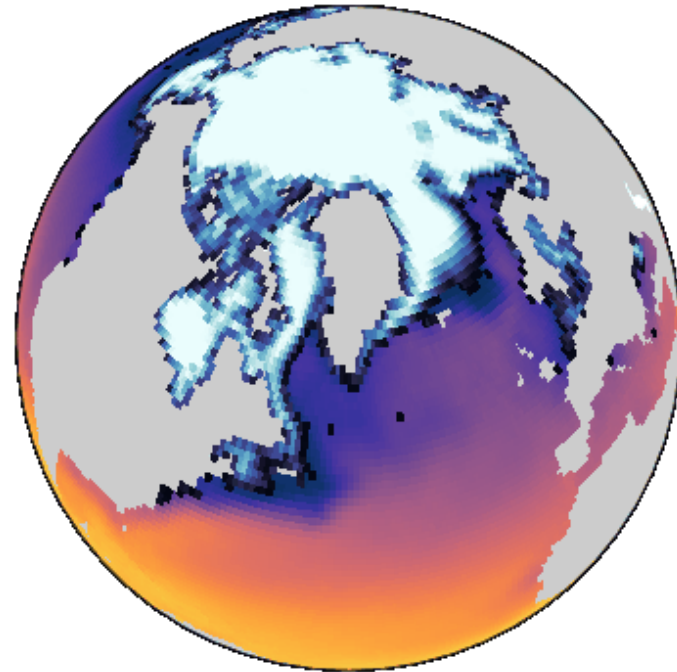


Samudra: Autoregressive AI ocean emulator



Example: SamudrACE (M2Lines & AI2)

- Coupling of climate-relevant physics
- 3D AI ocean-atmosphere-sea-ice climate emulator
- Enabling long-term projections at a fraction of the cost



Summary

- Climate emulators approximate complex Earth System Models to provide faster predictions and bridge physical simulations with societal impact needs
- They rely on high-quality training data and must remain stable, physically consistent, and realistic
- Pattern scaling is a simple emulator approach linking local changes to global temperature, but it captures mainly forced responses and lacks internal variability
- AI-based emulators (e.g., diffusion models, neural operators) can generate realistic high-resolution or temporal data and enable long, efficient climate simulations
- Key challenge: balancing speed with physical fidelity, especially for long-term trends, variability, and generalization across scenarios